NTCIP Standards Bulletin B0100

from the Joint AASHTO / ITE / NEMA Committee on the NTCIP

DATE: November 9, 2004

TO: AASHTO, ITE, and NEMA

SUBJECT: **User Comment Draft of NTCIP 1205 Amendment 1, *Object Definitions for Closed Circuit Television (CCTV) Camera Control***

ACTION: Request for Distribution to Solicit User Comments

RECOMMENDATION. This Bulletin reports that the Joint Committee on the NTCIP accepted the proposed NTCIP 1205 Amendment 1, *Object Definitions for Closed Circuit Television (CCTV) Camera Control*, as a User Comment Draft Amendment, and recommended to AASHTO, ITE, and NEMA that the draft be distributed to solicit user comments. The recommendation was made at the regularly scheduled meeting on August 26-27, 2004, and was approved by a majority of the committee members (10 yeas, no nays, no abstentions).

The Joint Committee on the NTCIP contributes to the joint standards development process by accepting a proposed draft document at two stages in its development – first as a User Comment Draft and then again as a Recommended Standard.

BACKGROUND. This document was developed to revise and amend a Joint AASHTO / ITE / NEMA Standards Publication. The 1205 Revision Amendment 1 proposes changes and updates to NTCIP 1205:2001, version 01.08. The NTCIP 1205 is in the 1200-series of NTCIP document numbers, and is a Device Data Dictionary document.

NTCIP 1205 defines an object set for controlling CCTV cameras. The object set provides for positioning the camera, adjusting the lens, and labeling the video image.

NTCIP 1205 Amendment 1 includes these proposed changes:

- divides the pan-tilt camera referencing system into vertical and horizontal systems;
- revises the Position Reference Object to define the type, direction, and speed of camera movement;

- adds Position Query Parameter objects for Preset, Pan, Zoom, Focus, and Iris;
- adds objects for Alarm Label Source Parameter, Zone Video Control, and others;
- corrects and clarifies various objects;
- adds an Annex B Information Profile of conformance groups defined by mandatory or optional tables of objects.

NTCIP 1205 was developed by the Joint Committee's CCTV Working Group, which is chaired by Michael Forbis (Washington State DOT). The CCTV WG started meeting in August 1997, and now has 14 members from both the public and private sectors.

NOTES. Previously, NTCIP amendments only referenced the clause that was being changed, and only excerpted the portion of the text that was being changed. However, this "revision amendment" was drafted and is being presented in the context of the complete document, with strikethrough text for proposed deletions and underline text for proposed additions.

By coincidence, the present version number of the draft amendment (1205 Amendment 1 v08) is the same as the minor version number of the jointly approved standard (1205 v01.08). After further revision and joint approval of Amendment 1, and incorporation of Amendment 1 into NTCIP 1205, the new standard publication version number is expected to be 1205 v01.09 or higher.

USER COMMENT INSTRUCTIONS. People who receive this request for comments are asked to follow these instructions.

1. Refer this Standards Bulletin and the draft document to the person or persons in your organization who are most familiar with, and concerned about, traffic management and NTCIP standards. Also refer this Bulletin to anyone involved with the design, deployment, or operation and maintenance of traffic management systems, including any consultants they may use.

2. Review any portion, or all, of the user comment draft. Any comments, however general or specific, will be appreciated.

3. Email, mail, or fax (in order of preference) your comments to:

email <ntcip@nema.org>
NTCIP Coordinator at NEMA
1300 North 17th Street, Suite 1847
Rosslyn, VA 22209-3801
fax (703) 841-3331

4. List each of your comments in the following five-part format:

document: NTCIP 1205 Amendment 1 v08
page number:
clause or paragraph number:
comment:
suggested change:

5. Please respond by the end of the comment period as instructed by your standards organization. For NEMA, the 30-day comment period for this Bulletin will close about December 10, 2004. For AASHTO, the 30-day comment period will also close about December 10, 2004. Comments received after the closing date will be accepted, but they may not be included in the next version of the document. Please include your name and mailing address so that your comments can be acknowledged.

ATTACH-MENT: 1. NTCIP 1205 Amendment 1 v08, *CCTV Camera Control*, amendment version v08a, November 2004, ~88 pages.

FROM:
NTCIP Coordinator
NEMA
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Rosslyn, VA 22209-3801
fax (703) 841-3331
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CC: Email with PDF attachment for redistribution to AASHTO and ITE staff.
Email notification to NTCIP community via listserve reflector for NTCIP Web site distribution.

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A User Comment Draft Amendment of the Joint Committee on the NTCIP

Revision Amendment 1 to
NTCIP 1205 v01.08

National Transportation Communications for ITS Protocol

Object Definitions for Closed Circuit Television (CCTV) Camera Control

A1 v08 August 2004
A1 v08a November 2004

This amendment is a set of proposed changes to NTCIP 1205:2001 v01.08, and that if jointly approved, will be published as an incremented minor version of major version v01. Because the proposed changes are located throughout the NTCIP 1205 v01.08 standards publication, the proposed Amendment 1 changes are presented by strikethrough (proposed deletions) and underline text (proposed additions), and identified by marginal change bars.

Published by

American Association of State Highway and Transportation Officials (AASHTO)
Institute of Transportation Engineers (ITE)
National Electrical Manufacturers Association (NEMA)

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ACKNOWLEDGEMENTS

This publication was prepared by the NTCIP CCTV Working Group which is a subdivision of the Joint Committee on the NTCIP. The Joint Committee is organized under a Memorandum of Understanding among the American Association of State Highway and Transportation Officials (AASHTO), the Institute of Transportation Engineers (ITE), and the National Electrical Manufacturers Association (NEMA). The Joint Committee on the NTCIP consists of six representatives from each of the standards organizations, and provides guidance for NTCIP development.

At the time that this document was prepared, the following individuals were active members of the NTCIP CCTV Working Group:

- Joseph Bowman
- Mike Forbis (chair)
- G. Curtis Herrick
- John Kalter
- John McDonough
- Emmanual Morala
- Bruce Pluth
- Glenn Regner
- Stephen L. Robinson
- Canny Quach
- Shahram Shahriari
- R. J. Surgi
- Phillip Tran
- Keith Vennel

In addition to the many volunteer efforts, recognition is also given to those organizations that supported the efforts of the NTCIP CCTV Working Group by providing comments and resources for the development of the standard, including:

- California Department of Transportation
- Cohu, Inc.
- Diamond Electronics, Inc.
- Federal Highway Administration
- ~~Gardner Transportation Systems, Inc.~~
- G. C. Herrick & Associates, Inc.
- Gresham Smith and Partners
- Gyyr, Inc
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- Los Angeles Department of Transportation
- Ontario Ministry of Transportation
- Pelco, Inc.
- Sensormatic Electronics Corporation
- Southwest Research Institute
- Videolarm
- Washington State Department of Transportation

FOREWORD

This document uses only metric units.

This document defines the Closed Circuit Television (CCTV) data elements, or objects, that are supported by the NTCIP.

The text includes an extended glossary in Annex A that is defined as informative.

For more information about NTCIP standards, visit the NTCIP Web Site at http://www.ntcip.org. For a hardcopy summary of NTCIP information, contact the NTCIP Coordinator at the address below.

In preparation of this NTCIP document, input of users and other interested parties was sought and evaluated. Inquiries, comments, and proposed or recommended revisions should be submitted to:

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National Electrical Manufacturers Association
1300 North 17th Street, Suite 1847
Rosslyn, VA 22209-3801
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Approvals

This document was separately balloted and approved by AASHTO, ITE, and NEMA after recommendation by the Joint Committee on the NTCIP. Each organization has approved this standard as the following standard type, as of the date:

AASHTO – Standard Specification; February 2001
ITE – Software Standard; May 2001
NEMA – Standard; July 2001

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All User Comments will be referred to the committee responsible for developing and/or maintaining this standards publication. The committee chairperson, or their designee, may contact the submitter for clarification of the User Comment. When the committee chairperson or designee reports the committee’s consensus opinion related to the User Comment, that opinion will be forwarded to the submitter. The committee chairperson may report that action on the User Comment may be deferred to a future committee meeting and/or a future revision of the standards publication. Previous User Comments and their disposition may be available for reference and information at www.ntcip.org.

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History

From 1997 to 1999, this document was referenced as TS 3.CCTV. However, to provide an organized numbering scheme for the NTCIP documents, this document is now referenced as NTCIP 1205. The technical specifications of NTCIP 1205 are identical to the former reference, except as noted in the development history below:

TS 3.CCTV v98.01.03. August 1998 – Accepted as a User Comment Draft by the Joint Committee on the NTCIP. October 1998 – Distributed by NTCIP Standards Bulletin B0028 for user comment.

NTCIP 1205 v01.07. July 1999 – Version 01.06 accepted as a Recommended Standard by the Joint Committee on the NTCIP. August 2000 – Version 01.07 attached to NTCIP Standards Bulletin B0055 included typographic corrections. Approved by AASHTO in February 2001, approved by ITE in May 2001, and approved by NEMA in July 2001.

NTCIP 1205:2001 v01.08, December 2001. January 2002 – Formatted for printing: updated title page date and version number; and revised the front matter to conform to NTCIP 8002. All references to TS 3 standard number were changed to equivalent NTCIP standard numbers.

INTRODUCTION

The purpose of this document is to define the Closed Circuit Television (CCTV) Camera Control objects that are supported by the NTCIP.

The *NTCIP Object Definitions for Closed Circuit Television (CCTV) Camera Control* defines objects in ASN.1 using the SNMP Object Type Macro for devices that sense the presence or similar characteristics of vehicles. These definitions are intended for CCTV camera control devices.

This standard defines requirements that are applicable to all NTCIP environments and it also contains optional and conditional clauses that are applicable to specific environments for which they are intended.

The following keywords apply to this document: AASHTO, ITE, NEMA, NTCIP, CCTV, camera control, objects.

In 1992, the NEMA 3-TS Transportation Management Systems and Associated Control Devices Section began the effort to develop the NTCIP. ~~The Transportation Section's purpose was to respond to user needs to include standardized systems communication in the NEMA TS 2 standard, *Traffic Controller Assemblies*.~~ Under the guidance of the Federal Highway Administration's NTCIP Steering Group, the NEMA effort was expanded to include the development of communications standards for all transportation field devices that could be used in an Intelligent Transportation Systems (ITS) network.

In September 1996, an agreement was executed among AASHTO, ITE and NEMA to jointly develop, approve, and maintain the NTCIP standards. In August 1997, the Working Group was first organized to develop data element definitions for Closed Circuit Television camera control. ~~Under the guidance of the Joint AASHTO/ITE/NEMA Committee on the NTCIP, a Working Group was formed to develop the object definitions for Closed Circuit Television camera control. The CCTV WG first met in August 1997.~~

~~The *NTCIP Object Definitions for Closed Circuit Television (CCTV) Camera Control* defines objects in ASN.1 using the SNMP Object Type Macro for devices that sense the presence or similar characteristics of vehicles. These definitions are intended for CCTV camera control devices.~~

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CONTENTS

Section 1
CCTV OVERVIEW

1.1 INTRODUCTION TO CCTV

The context of the NTCIP is one part of the Intelligent Transportation Systems (ITS) standardization activities covering base standards, profiles, and registration mechanisms.

- Base Standards define procedures and rules for providing the fundamental operations associated with communications and information that is exchanged over fixed-point communications links.

- Profiles define subsets or combinations of base standards used to provide specific functions or services. Profiles prescribe particular subsets or options available in base standards necessary for accomplishing a particular function or service. This provides a basis for the development of uniform, nationally recognized conformance.

- Registration Mechanisms provide a means to specify and uniquely identify detailed parameters within the framework of base standards and/or profiles.

Other working groups of the Joint AASHTO/ITE/NEMA Committee on the NTCIP are concerned with the methodology of defining profiles, and their documentation in Standards Publications. The objective is to facilitate the specification of ITS systems characterized by a high degree of interoperability and interchangeability of its components.

This document covers the control and status requirements of cameras, lenses, pan/tilt units. Video switches are an integral part of many CCTV systems, however, NTCIP standards for controlling video switches will be issued as a separate standards document. A CCTV Camera Control subsystem is comprised of an assembly of camera, lens, and pan/tilt functions.

There are no existing standards that define how these devices communicate with other related equipment. As a result, each manufacturer has developed its own protocol to meet their particular needs. To integrate systems manufactured by different companies, considerable extra work must be performed resulting in increased costs. This shortcoming limits interchangeability of components between different vendors and restricts the sharing of information and control within and between user organizations.

These problems have not been limited to CCTV surveillance systems. Many other devices also need to share network infrastructure and exchange information. In surface transportation, examples include traffic signal controllers, dynamic message signs, bus priority sensors, etc. To address these problems, the NTCIP is developing a family of open standards for communications among field devices and between field devices and central management stations, known as Traffic Management Subsystems (TMS).

The NTCIP CCTV standard describes objects that control the camera subsystem. As previously mentioned, objects that control video switches will be issued under separate cover.

1.2 BENEFITS OF STANDARDIZATION

As transportation systems become more sophisticated, planners, users, and equipment manufacturers recognize the need for system interoperability and integration. Currently, there is no common protocol with which different types of equipment can communicate. If CCTV is to be integrated with ITS, common communications standards must be established.

Before the NTCIP development started, each vendor of electronic devices used in transportation adopted

a different protocol for data communications. This made it very difficult to mix equipment from different vendors in the same system, and to communicate between systems operated by adjacent agencies. The NTCIP is now providing a common standard that can be used by all vendors.

The NTCIP offers increased flexibility and choice for agencies operating traffic management systems. It removes barriers to inter-jurisdictional coordination and allows equipment of different types and manufacturers to be mixed on the same communications line. For these reasons, operating agencies will benefit from specifying that the NTCIP is included in all future purchases and upgrades.

Benefits of adopting open standards based on the NTCIP include:

- *Avoiding Early Obsolescence*: Though it may not be practical to retrofit NTCIP support in some old equipment, most CCTV vendors will offer NTCIP support in current and future products. An operating agency can ensure that its equipment remains useful and compatible long into the future by requiring NTCIP support for all future purchases and upgrades. This will include central computers and CCTV field devices, such as cameras, pan/tilt mechanisms, lens, and video switchers.
- *Providing Choice of Vendor*: Once an agency has a CCTV surveillance system that includes support for NTCIP it can buy field devices from any manufacturer offering NTCIP-compatible products, and they will communicate with the agency's "Traffic Management Subsystem" ('TMS', typically termed CPU).
- *Allowing Interjurisdictional Coordination*: In the future, an agency may want to communicate with CCTV devices owned by other users and/or procured from different vendors. Under NTCIP, these various devices can be added onto an existing communications channel and mixed with different types of devices on the same line.
- *Using one Communications Network for All Devices*: NTCIP also allows a central computer to communicate with a range of field devices on the same communications channel. For example, if a dynamic message sign is installed near a CCTV camera control receiver, the central computer could communicate with the sign controller using the communications channel already in place for the CCTV camera control receiver. The communications network is usually the most expensive component of a transportation management system and use of the NTCIP maximizes that investment.

Several state and local transportation agencies already have a number of CCTV surveillance systems deployed for traffic and transportation management. At present, however, these systems often include proprietary elements that limit expansion and upgrade opportunities.

The development of the NTCIP will allow a more open-systems approach, not only among CCTV equipment, but also with a wide variety of other field devices. It is expected that this open-systems approach will result in lower deployment and equipment costs similar to the PC industry. This in turn will allow for more devices to be deployed resulting in better decision-support to decrease maintenance costs.

To make best use of these advancements, CCTV should be viewed in the much broader context of Intelligent Transportation Systems (ITS). The key to these benefits is open standards, allowing agencies to share data and avoid becoming locked into proprietary systems.

1.3 EXISTING STANDARDS

There are great benefits of adopting existing standards where possible. These include:

- reuse of software modules during development
- faster implementations
- reducing risks
- ability to integrate components from different manufacturers
- unambiguous meanings of terminology
- building on proven technologies

1.3.1 Internet Standards

The Internet Engineering Task Force (IETF) is responsible for developing and maintaining the standards, guidelines and procedures for communications over the Internet. This group has become increasingly important over the last few years as the Internet has gained popularity. A wide range of Internet standards exist, including:

- Point-to-Point Protocol (PPP) - which may be used for NTCIP dial-up links
- Internet Protocol (IP) - which may be used for NTCIP communications over networks
- Transport Control Protocol (TCP) - which may be used to provide connection-oriented transport services over NTCIP networks
- User Datagram Protocol (UDP) - which may be used to provide connectionless transport services over NTCIP networks
- Simple Network Management Protocol (SNMP) - which may be used to exchange NTCIP data elements such as those defined within this document.

1.3.2 International Organization of Standardization Standards

The International Organization of Standardization (ISO) also develops various communication standards among a wide variety of other standards. The Open Systems Interconnect Reference Model (OSI) is a widely-referenced ISO standard which defines the standard seven-layered communications model. While most implementations do not strictly conform to this standard, virtually all modern communications schemes, including the NTCIP, use many of the concepts defined within the standard. In addition, NTCIP communications may use the High Level Data Link Control Protocol (HDLC), another ISO standard, in specifying how to send a message over a single communications link.

1.3.3 NTCIP

To support ITS developments, US DOT funded the design of a National ITS Architecture. This architecture defines major ITS subsystems and the needs for information exchange among them. The National Transportation Communications for ITS Protocol (NTCIP) group is now developing standards for these information exchanges. NTCIP – a joint initiative of AASHTO, ITE, and NEMA – recognizes that closed circuit television is a vital component of traffic and transportation management systems. The family of NTCIP standards will enhance CCTV implementation and provide a mechanism for the manipulation of the basic camera control functions within CCTV systems.

1.3.4 NTCIP System Design

NTCIP was initially designed to support traffic signal controllers because that was seen by the FHWA as an area of most pressing need. However, the development process planned that the protocol would be extended to other transportation environments (e.g., ITS) and, where appropriate, to other environments.

The NTCIP family of protocols is continually expanding to address additional needs. Work is in progress on additional protocols for computer-to-computer or center-to-center data exchange, transit communications, and communications with or between moving vehicles. The NTCIP, along with other US DOT standards efforts, will eventually provide a comprehensive family of communications protocols covering all appropriate ITS applications.

There may also be a future demand to use the system for communications to field devices that are not transportation related. The ultimate scope of NTCIP cannot be rigidly determined. The key is to determine how those changes might affect the system design and to provide flexible standards that accommodate these changes. NTCIP will seek to utilize existing telecommunications and computer industry standards to the extent possible.

1.4 CLOSED CIRCUIT TELEVISION

Closed Circuit Television (CCTV) is a method of distributing video signals such that access to said signals is confined to devices directly connected to a common circuit or system. By contrast, broadcast

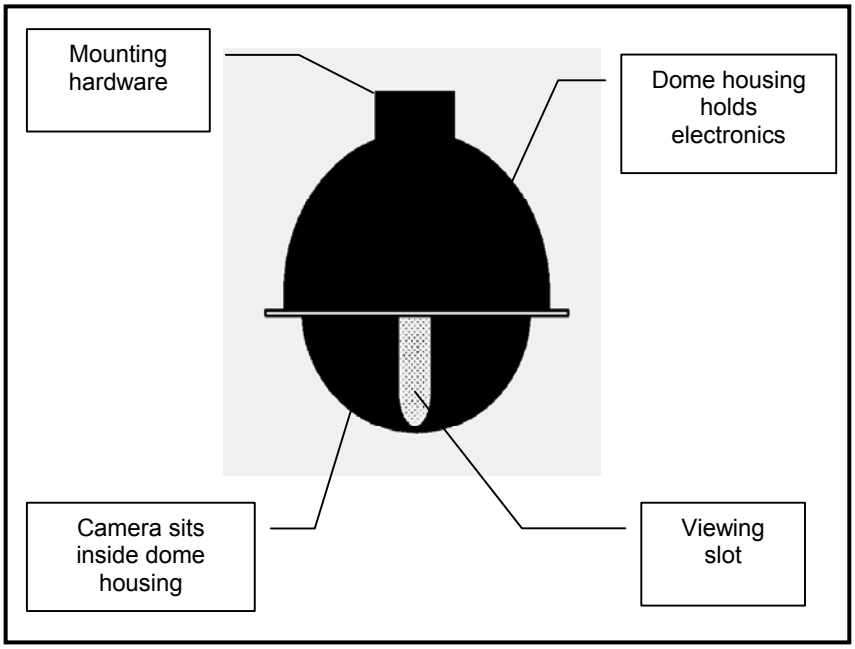
television signals are available to an unlimited number of receivers, and access to such signals cannot easily be restricted or controlled.

CCTV video information is then normally transmitted within a closed system through a restricted-access medium in the form of signals conforming to the RS170 standard for video signaling. This signaling is characterized by the combination of a voltage-encoded video luminance (brightness or intensity) signal, a color signal encoded on an amplitude-and-phase-modulated carrier, and additional voltage encoded synchronization signals. Since the luminance and synchronization signals are not modulated, RS170 video is referred to as "base-band video". Also because the brightness, color and synchronization signals are combined onto a single wire, RS170 is characterized as "composite video". By contrast, broadcast TV signals are also composite video, but are amplitude modulated onto pre-established frequency carriers to permit transmission of multiple channels over a common medium.

Each base-band, composite video signal in a CCTV system is normally transmitted over a dedicated coaxial cable. However, CCTV signals are often modulated and/or combined for transmission over fiber optics cables or other access-secured transmission media to increase transmission distances or to achieve cost savings.

Video signal transmission is currently outside the scope of the NTCIP. Standards for video transmission may be added at some later date, but will not be discussed in this document. In addition to the video signal, CCTV systems provide a data communications connection between the traffic management center and field devices for the purpose of manipulating camera position, lens adjustment, and video switching. Camera positioning includes panning the camera in the horizontal plane both right and left, and tilting the camera in the vertical plane both up and down. Lens adjustments include zoom adjustments for wide and telephoto, focus adjustments for both far and near, and iris adjustments for both closed and open. Video switching devices provide a mechanism for manipulating input and output assignments to effectively utilize available network capacity. This document specifically addresses the data communications link between the traffic management center and the field devices that is used for the camera control.

For simplicity, the control of the pan/tilt unit, lens, and camera will be assumed to use the same physical channel and target control processor called a camera control receiver. The camera control receiver receives the data communication and generates the necessary control signals for individual CCTV components such as the lens. The concept of the camera control receiver does not preclude each CCTV device from directly processing the NTCIP messages, as system architecture can vary among manufacturers.



The number of camera adjustment features has increased dramatically as new technology continues to press the video surveillance industry. Today's CCTV systems have a diverse set of features that vary depending on manufacturer. A basic array of these features covering configuration, motion and lens control, alarms, inputs, outputs, labels, camera menu manipulation, and the video switch are supported by the NTCIP standards.

The NTCIP CCTV Camera Control standard describes objects that control the camera subsystem. As previously mentioned, objects that control video switches will be issued under separate cover.

1.4.1 Discussion of CCTV Coordinate Systems

There are two CCTV coordinate systems referenced in this standard. The horizontal coordinate system is used for pan positioning and the vertical coordinate system is used for tilt positioning.

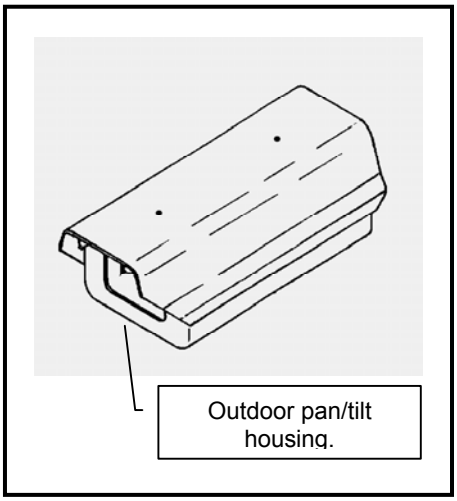
1.4.1.1 Horizontal Coordinate System

A dome CCTV camera enclosure has a clear viewing slot that can be rotated, or "panned", to a user selected viewing position. To be able to repeat positions, the dome has the ability to measure the direction that the camera is pointing.

The mechanism that controls the pan and tilt movement will have a "home" position, or a "native" zero. The home location depends on how the device was installed, as the device could be pointing in any direction.

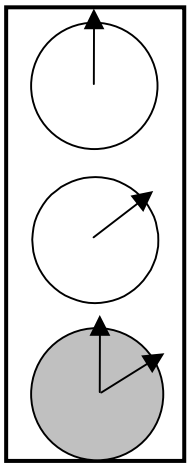
This means that, if the pan mechanism is told to go to an angle of 30 degrees, it will comply but the operator will not know where that position really is located. If the equipment is installed so that the dome's native coordinate system is aligned with a local, or global, coordinate system, that will solve the direction problem.

Unfortunately, another problem also exists. Circular movement is most often discussed in terms of degrees. A circle is divided into 360 degrees. Unfortunately, a pan/tilt mechanism is very unlikely to have the same units of measurement. A pan device might, for example, have a pan movement that is controlled through 256 steps, or divisions, within a circle. The number of steps might also be defined as 641, or some other vendor specific value.



This standard seeks to resolve these problems by describing a reference between the coordinate system of the device and some other local or global coordinate system. The following two-step solution for resolving the coordinate system dilemma is employed by this standard:

1. Provide for a standard conversion mechanism to convert between a pan/tilt device's native coordinate system and a local or global coordinate system.
2. Specify and use a universal measurement system, which in this case is defined as degrees.



An example should help to make this clear. Let's suppose that a new pan/tilt mechanism has just been installed. The coordinate system at the device level is fine for use, but there is a need for the device to recognize true north (a global coordinate system in this case) as being 0 degrees.

When we look down on the object from above, true north is in the direction shown in the top illustration circle.

Unfortunately, the device as installed, regards the direction shown in the middle illustration circle as being the direction of 0 degrees (also known as the Home Position). Let us assume for the purposes of this example that the Home Position is located 60 degrees clockwise from True North.

To make the coordinate system of the pan/tilt mechanism match the true north direction, the device must be told what the difference, or True North Offset, is between the direction of actual true north and the direction that the device recognizes as 0 degrees. In the example shown, the device would be told that the true north offset is ~~+60~~ 300 degrees away from the native 0 degrees heading.

One way of performing this exercise with field equipment might be to aim the device toward true north and then tell the device that here is the location of what I want to call 0 degrees. ~~The device can then remember that offset value.~~ The management system can request the value of True North Offset from the device and make the necessary calculations to determine the appropriate reference from the Home Position.

From that time forward, the ~~device will~~ management station will perform a conversion on any position references that it ~~hears~~ receives, and reference any movement from the Home Position. If the operator ~~sends a request~~ wants to move the camera to a heading of 270 degrees from true north, the management station will request the value of the True North Offset ~~the device will receive that heading~~, add ~~60~~ 300 degrees to it (giving a local reference heading of ~~330~~ 210 degrees), and direct the device to go to that heading. The calculations are described as follows:

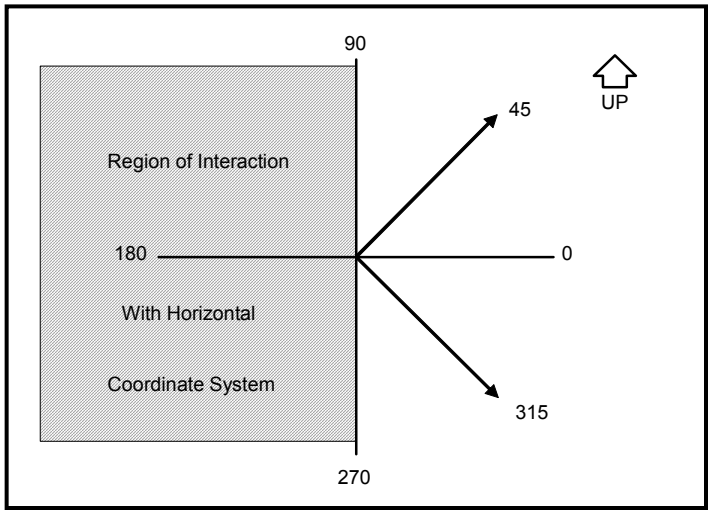
- True North = 0 degrees for the global coordinate system;
- Home Position = 0 degrees for the device coordinate system, but it is really located at 60 degrees for the global coordinate system;
- The True North Offset is calculated as the difference from the Home Position to True North measured in the clockwise direction, and this value is 300 degrees (a complete circle at the Home Position is 360 degrees less the 60 degree difference between True North and the Home Position;
- To move to a position of 270 degrees from True North on the global coordinate system, the device would have to be moved 210 degrees from the Home Position on the device coordinate system (start with 300 degrees of True North Offset and add 270 degrees, however we have completed an entire revolution of the circle and must now subtract 360 degrees to give the local reference heading of 210 degrees).

This offset allows the user to establish an arbitrary frame of reference for the pan/tilt mechanism.

This standard employs a single measurement format for universally describing horizontal and vertical positioning. The measure chosen is hundredths of degrees. All pan/tilt devices must accept measures that are in the range 0.00 degrees to 359.99 degrees.

Most devices will not be capable of this degree of accuracy nor will they necessarily divide a circle up into 360 even steps. The manufacturer is responsible for rounding to the appropriate nearest level of accuracy and for converting to (as nearly as possible) a circle measured in degrees.

These conversions provide for a common interface that will ensure system level interoperability.



1.4.1.2 Vertical Coordinate System

The vertical coordinate system is based upon a 360 degree circle on a vertical plane that extends through the camera's movement point and the center of the earth. The zero point for measurement is any point on the

horizontal plane. The horizontal plane is orthogonal to the vertical line extending from the camera's movement point and the center of the earth. Tilting upward indicates a positive direction of movement. The figure to the right shows the vertical coordinate system.

With the definition of the zero point of measurement for the vertical coordinate system being any point along the horizontal plane, there is an interaction between the horizontal and vertical coordinate systems. As a result of this interaction, queries for tilt position are always returned as values between 270 degrees to 359.99 degrees and 0 degrees and 90 degrees. This means that if the camera direction points to a position behind the vertical line, the horizontal coordinate system must be adjusted by 180 degrees in order to compensate for the new camera tilt direction reporting criteria. An example of horizontal and vertical coordinate system interaction is given, as follows:

- Start with the pan position of the camera pointing in the direction of the Home Position with a True North Offset being zero (0) degrees, resulting in a horizontal coordinate system value of zero (0) degrees;
- The tilt position of the camera is pointing in the direction of 345 degrees (45 degrees below the horizontal plane;
- The queries for camera position are reported as zero (0) degrees in the horizontal coordinate system and 345 degrees in the vertical coordinate system;
- The camera tilt position is then moved to a point of 225 degrees (45 degrees below the horizontal plane, but behind the vertical line through the camera's movement and the center of the earth) while the pan position remains at a value of zero (0) degrees;
- At the point in which the the tilt position passes through the vertical line through the camera's movement and the center of the earth, the horizontal coordinate system must be adjusted such that the camera tilt position can be reported as values between 270 degrees to 359.99 degrees and 0 degrees and 90 degrees.
- The resulting camera position would be reported as 180 degrees from the Home Position in the horizontal coordinate system and 345 degrees in the vertical coordinate system.

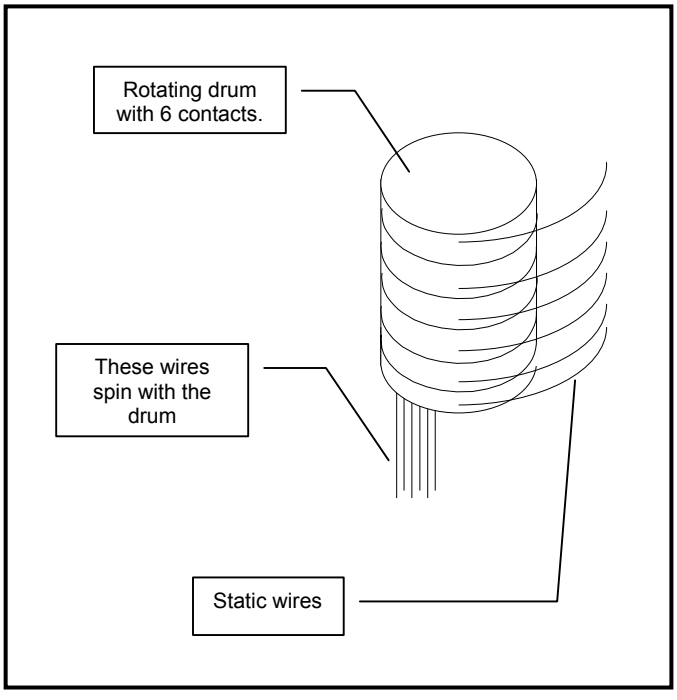
1.4.2 Discussion of Limit Stops in CCTV Systems

Many CCTV devices use limit stops. A limit stop is a mechanical or software device that ensures that the range of movement of a system stays within an acceptable range. Limit stops are commonly found on lenses and pan and tilt mechanisms.

Limit stops on lenses are present to limit the range of zoom, focus, and iris movement to what can be accommodated by the lens mechanics. The physical range of movement allowed for zoom movement, for example, is limited by the lens' track length.

Limit stops on pan and tilt devices can be either for limited mechanical motion (as in non-slip ring devices), legal reasons (you can't allow the camera to point toward the apartment complex), or for other practical reasons (no point in pointing the camera at the wall it's mounted on).

In non-slip ring pan and tilt mechanisms, the camera is connected to the outside world by a cable. This cable can only be twisted just so far before the cable will fail. It's common to have a "dead zone" or area the camera cannot see because of this limit. These limits, in most systems, can be moved so that the dead zone



can be placed where it will do no harm to the functionality of the system and are typically a few degrees wide.

Systems using slip rings, as shown in the illustration are capable of 360° movement without restriction. That is, these systems can spin in one direction without limit. A slip ring consists of a set of static wires that ride in a grooved drum. Each wire is bare on the end and makes electrical contact with the surface inside the grove in the rotating drum. The drum also has a set of wires that move with the rotating object (in CCTV this is the camera). Electronic messages, and voltage can then be applied, to a rotating assembly, without twisting wires. Occasionally, systems using slip rings will need to be used in places where limits must be applied. When they're applied, these units work like the non-slip ring units.

Many systems allow you to control the width of this dead zone along with its placement. With physical limit stops you would move a switch, or a block to the appropriate position and lock it in place. With software limit stops you aim the camera at one edge, then tell the system to remember this limit position.

The left limit stop is that stop that is reached when you pan to the left. That is, the image on the monitor indicates that the camera is turning to the operators left. This provides an unambiguous reference as to what is left, or right.

This standard provides a mechanism for setting pan, tilt, zoom, focus, and iris range limits.

1.4.3 Discussion of PositionReference Object

The PositionReference object is defined by a four (4) Byte OCTET STRING denoting those parameters that are required to control the detailed movement of the camera. Byte 1 of PositionReference defines the choice of mode for the following types of movement:

- stopMovement – bit value 00 meaning a cessation in camera movement,
- delta – bit value 01 meaning an incremental camera movement,
- absolute – bit value 10 meaning movement to an absolute position value, and
- continuous – bit value 11 meaning to start moving and continue until told to stop.

Byte 2 denotes the direction and speed of the movement, as follows:

- speed – signed INTEGER, with a range of -127 to +127, defining the speed and direction of movement.

  It should be noted that the device is not required to support variable speeds. However, if variable speeds are supported, then the speeds of -1 and +1 are the slowest speed for a given direction of movement. Likewise, speeds of -127 and +127 are the fastest speeds for a given direction of movement. The value of 0 means a stoppage in movement. The direction of movement is denoted by the positive (+) and negative (-) portion of the signed values.

And, Bytes 3 and 4 denote the offset value, as follows:

- offset – two Byte INTEGER, with a range of 0 to 65535, defining the position or offset value.

*Example 1 – Use of the **stopMovement** Mode of Movement*

When the stopMovement choice is used, Byte 1 contains a bit mapped value of 00 indicating the choice of the stop movement command. Byte 2 has a value of 0, indicating a stoppage in movement. Bytes 3 and 4 are ignored for the stopMovement choice of movement modes.

*Example 2 – Use of the **delta** Mode of Movement*

When the delta choice is used, Byte 1 contains a bit mapped value of 01 indicating the mode choice of the delta movement command. Byte 2 is a signed INTEGER with a value between +1 and +127 or -1 and -127, with the value indicating the speed and the sign, positive (+) or negative (-), indicating the direction of movement. Bytes 3 and 4 are an INTEGER value between 0 and 65535 specifying the incremental

amount of movement. For those objects where the increment is given in 1/100th degrees of movement, then the acceptable values for Bytes 3 and 4 are 0 to 35999. For those objects where the increment is given as a scalar value, then the acceptable values for Bytes 3 and 4 are 0 to 65535. For offsets yielding values beyond the limits, the device moves to the limit and stops.

*Example 3 – Use of the **absolute** Mode of Movement*

When the absolute mode choice is used, Byte 1 contains a bit mapped value of 10 indicating the mode choice of the absolute movement command. Byte 2 is a signed INTEGER with a value between +1 and +127 or -1 and -127, with the value indicating the speed and the sign, positive (+) or negative (-), indicating the direction of movement. However, the direction of movement is ignored for the absolute mode choice and the speed of movement is the value of the signed INTEGER. Bytes 3 and 4 are an INTEGER value between 0 and 65535 specifying the absolute value to which the device is to be moved, measured from the Home Position, with movement taking the shortest allowable path. For those objects where the absolute value of movement is given in 1/100th, then the acceptable values for Bytes 3 and 4 are 0 to 35999. For those objects where the absolute value of movement is given as a linear value, then the acceptable values for Bytes 3 and 4 are 0 to 65535.

*Example 4 – Use of the **continuous** Mode of Movement*

When the continuous mode is used, Byte 1 contains a bit mapped value of 11 indicating the mode choice of the continuous movement command, meaning to start moving and continue to move until another movement command is issued, or the device times out. Byte 2 is a signed INTEGER with a value between +1 and +127 or -1 and -127, with the value indicating the speed and the sign, positive (+) or negative (-), indicating the direction of movement. Bytes 3 and 4 are ignored for the continuous choice of movement modes.

1.4.4 Discussion of Zones

This standard allows for the establishment of user definable zones. A zone is a region in space that is defined by the pan and tilt limits of the device. As the device moves, zones may be encountered. Various actions may occur upon entering a zone. Such actions include displaying a label or turning off the video output. A defined zone where the associated action is to turn off the video output is sometimes referred to as a privacy zone by the user community. This standard allows for up to 255 zones to be defined.

It is expected that zones will not overlap. However, in the event that zones do overlap and labels are to be displayed while in the zone, at least one label will be displayed in the overlapped area.

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Section 2
GENERAL

2.1 SCOPE

The communications between an ITS Management Center or portable computer and ~~an~~ a Closed Circuit Television (CCTV) Camera Controller is accomplished by using the NTCIP Application Layer services to convey requests to access or modify values of CCTV Camera Control objects resident in the device via an NTCIP network. An NTCIP message consists of a specific Application Layer service and a set of data objects. An NTCIP message may be conveyed using any NTCIP defined class of service that has been specified to be compatible with the Simple Transportation Management Framework (STMF).

The scope of this document is limited to the functionality related to CCTV Camera Control within a transportation environment. This publication defines objects which are specific to CCTV and also defines standardized object Groups which can be used for conformance statements. The limits and descriptions of the parameters are established to give the user maximum flexibility to operate devices that either exist at the time this document was authored or may exist in the future.

2.2 REFERENCES

For approved revisions, contact:

NTCIP Coordinator
National Electrical Manufacturers Association
1300 North 17th Street, Suite 1847
Rosslyn, VA 22209-3801

For proposed revisions which are under discussion by the relevant NTCIP Working Group, and revisions recommended by the Joint Committee on the NTCIP, browse to the Web at http://www.ntcip.org.

The following standards (normative references) contain provisions that, through reference in this text, constitute provisions of this Standard. Other documents and standards (other references) are referenced in these documents, which might provide a complete understanding of the entire protocol and the relations between all parts of the protocol. At the time of publication, the editions indicated were valid. All standards are subject to revision, and parties to agreements based on this Standard are encouraged to investigate the possibility of applying the most recent editions of each standard listed below.

2.2.1 Normative References

NEMA	NTCIP 1201 v01	*National Transportation Communications for ITS Protocol – Global Object Definitions*
RFC1212	03/26/1991	*Concise MIB Definitions*
RFC1213	03/1991	*Management Information Base for Network Management of TCP/IP-based Internets: MIB-II.*
RFC1155	05/10/1990	*Structure and Identification of Management Information for TCP/IP-based Internets*

2.2.2 Other References

2.2.2.1 ~~NEMA~~ Standards Related

NEMA	NTCIP 1101	*National Transportation Communications and ITS Protocol – Simple*

		Transportation Management Framework
NEMA	NTCIP 2001	*National Transportation Communications for ITS Protocol – Class B Profile*
ISO/IEC	8824-1995	*Information Technology - Open Systems Interconnection - Specification of Abstract Syntax Notation One (ASN.1)*
ISO/IEC	8825-1995	*Information Technology - Open Systems Interconnection - Specification of Basic Encoding Rules for Abstract Syntax Notation One (ASN.1)*
RFC1157	05/10/1990	*A Simple Network Management Protocol (SNMP).*

2.2.2.2 Texts

David Perkins and Evan McGinnis, *Understanding SNMP MIBs*, New Jersey, Prentice Hall PTR, 1997, ISBN 0-13-437708-7.

2.2.3 Contact Information

2.2.3.1 ISO/IEC Standards

Members of the ISO maintain registers of currently valid ISO/IEC International Standards. For the USA, the member of ISO is the American National Standards Institute (ANSI), which may be contacted as follows:

ANSI
11 West 42nd Street, 13th Floor
New York, New York 10036
(212) 642-4900

2.2.3.2 RFC Documents

Electronic copies of RFC documents may be obtained using “anonymous” FTP to the host nic.ddn.mil or ds.internic.net. Printed copies are available from:

DDN Network Information Center
14200 Park Meadow Drive
Suite 200
Chantilly, VA 22021
(800) 365-3642
(703) 802-4535

2.3 TERMS

For the purposes of this standard, the following terms and definitions apply. For terms not defined in this clause, English words are used in accordance with their definitions in the latest edition of *Webster's New Collegiate Dictionary*. Electrical and electronic terms not defined in this clause or in *Webster's New Collegiate Dictionary* are used in accordance with their definitions in IEEE Std 100-1992.

Absolute	A measure of pan, tilt, or zoom movement specified as the number of degrees relative to home position.
Alarm	An abnormal system condition that typically requires acknowledgement and correction by trained personnel.
Automatic Pan (Scan)	Continuous, automatic horizontal back and forth motion of a camera.
Auto Focus	The process of automatically adjusting the lens focus to provide a sharp image on the faceplate of the camera pickup device.

Auto Iris Lens	A lens where the aperture automatically opens or closes to maintain proper light levels on the faceplate of the camera pickup device.
Camera Power	The power supply delivered to the camera necessary for proper operation.
CCTV	Closed Circuit Television, any television system that transmits video information over a hardwire medium such as coax, fiber optic, twisted pair cable.
CCU	Camera Control Unit. A device used to multiplex and distribute multiple camera motion and lens position control inputs to multiple cameras. CCTV is also a distribution system that limits reception of an image to those receivers or monitors which are directly connected to the organization point by coaxial cable or microwave link.
Delta	A measurement in degrees of pan, tilt, zoom movement specified as the difference between an initial and final position.
Focus	The process of sharpening a blurred image on a screen, monitor, or any display; adjusting picture to achieve the greatest possible resolution.
Heater	A device used to maintain a constant camera enclosure temperature. A heater is typically thermostatically controlled and is used in harsh viewing environments.
Home Position	An arbitrary pan, tilt, and zoom position defined by the camera vendor. The home position represents a mechanical reference point from which camera and lens position parameters are measured.
Iris	A device used to control the amount of light that reaches the imaging sensor. The amount of light transmitted through a lens is controlled by an adjustable ~~diaphram~~ diaphragm, or iris, located in the lens barrel. The opening is referred to as the aperture, and the size of the aperture is controlled by rotating the aperture control ring on the lens barrel. The graduations on the lens barrel are expressed in terms of the focal length for the lens divided by the diameter of the aperture at that setting. This ratio is called the f-number.
Label	Text information embedded in the video and displayed on a monitor.
Lens	An assembly of optical components, usually made from glass, used to focus light on an imaging device.
Manual Focus	The process of manually adjusting the lens focus to provide a sharp image on the faceplate of the camera pickup device.
Manual Iris Lens	A lens in which the aperture is manually opened or closed to maintain proper light levels on the faceplate of the camera pickup device.
Octet Encoding Rules	A variation of Basic Encoding Rules (BER) developed for low bandwidth communications links.
Pan	Movement of the camera in a horizontal direction.
Preset	A pre-specified position where a camera is pointed to a fixed point in space. A preset includes pan, tilt, and zoom parameters. Presets are typically programmed by manually adjusting the camera position and lens zoom setting followed by initiating a save command from the

	camera control system.
Sequential Switcher	A video control device that switches multiple video inputs to multiple video outputs in a predetermined timed sequence.
Switcher	Term often used to describe a special effects generator; a unit that allows the operator to switch between video camera signals. Switchers are often used in industrial applications to switch between video cameras monitoring certain areas for display on one monitor.
Tilt	The movement of a camera in a vertical direction.
Video	Pertaining to picture signals in a television system. (A): any production using videotape or television technology. (B): Television and the technical equipment and events involved in creating television. (C): The picture portion of a television broadcast. (D): Non-broadcast or private television.
Zone	A region in space defined by pan and tilt limits. A zone is typically identified by a pre-programmed text message that is displayed to the user when the center of the camera's field of view is within the zone.
Zoom	The process of mechanically or electronically adjusting the focal length of a lens from wide angle through telephoto.

2.4 ACRONYMS

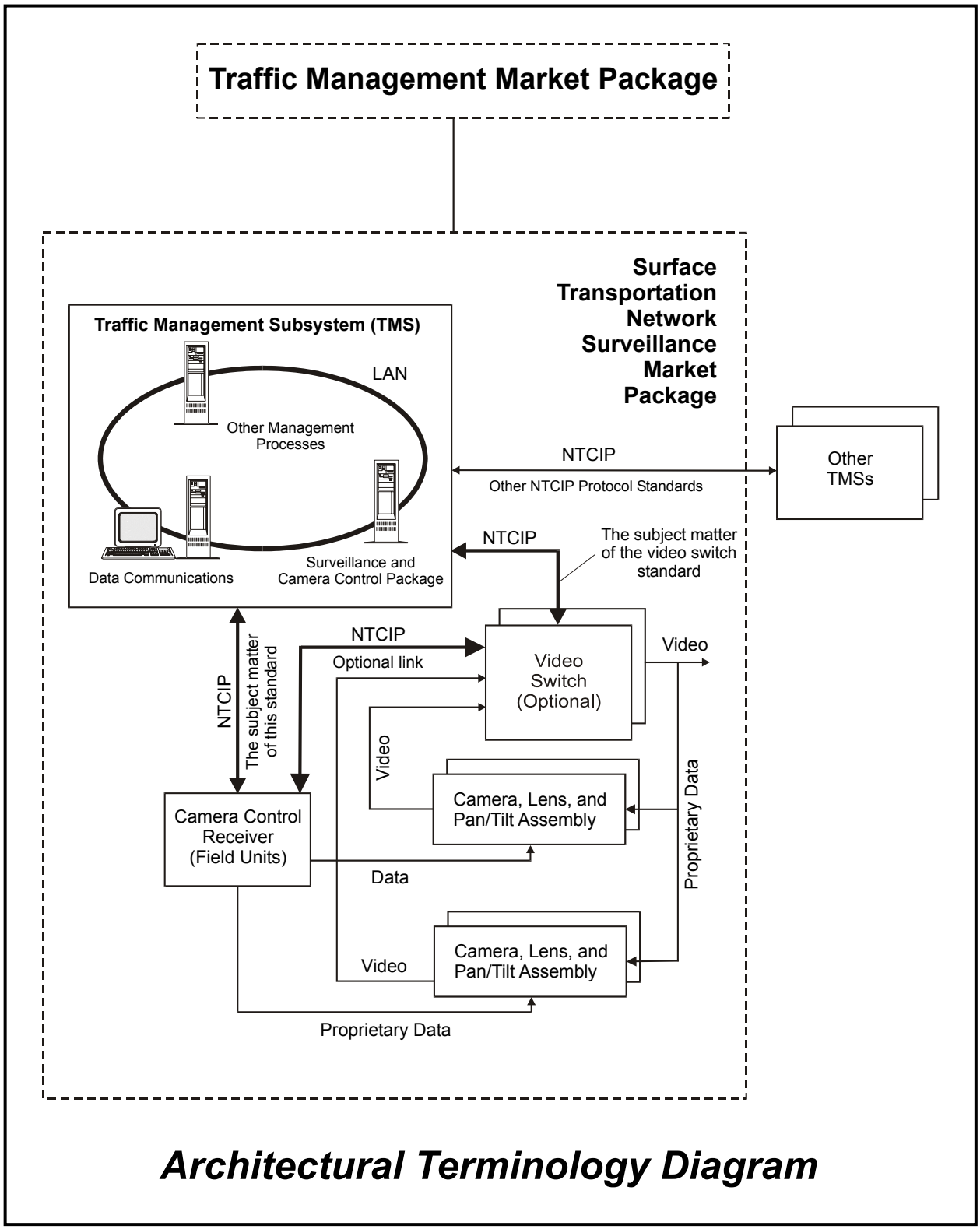
The following acronyms are widely used in either the Transportation or CCTV industry. For additional information, please refer to the extended glossary in ~~Informative~~ Annex A.

AASHTO	American Association of State Highway and Transportation Officials
ACTV	Advanced Compatible Television
ADTV	Advanced Definition Television
AFC	Automatic Frequency Control
AGC	Automatic Gain Control
AIV	Advanced Level Control Video
ALC	Automatic Level Control or Automatic Light Control
ASC	Automatic Sensitivity Control
CATV	Community Antenna Television
CAV	Component Analog Video
CCD	Charge-Coupled Device
CCTV	Closed Circuit Television
CCU	Camera Control Unit
CD	Compact Disc
CD+G	Compact Disc+Graphics
CD-I	Compact Disc-Interactive
CD-IV	Compact Disc-Interactive Video
CD+MIDI	Compact Disc-Musical Instrument Digital Interface

CD-ROM	Compact Disc-Read Only Memory
CLUT	Color Look-Up Table
EDTV	Enhanced Definition Television also Extended Definition Television
HDTV	High-Definition Television
IAB	Internet ~~Advisory~~ Architecture Board
ITE	Institute of Transportation Engineers
ITS	Intelligent Transportation Systems
LLTV	Low Light Television
MIB	Management Information Base
NEMA	National Electrical Manufacturers Association
NTCIP	National Transportation Communications for ITS Protocol
NTSC	National Television System Committee
OER	Octet Encoding Rules
PAL	Phase Alternate by Line
PAL-M	Phase Alternate by Line (Brazilian standard)
RFC	Request for Comment
RGB	Red, Green, Blue
SECAM	SEquetial Couleur A Memoire
STD	Standard
VDA	Video Distribution Amplifier
VITC	Vertical Interval Time Code
VTR	Video Tape Recorder

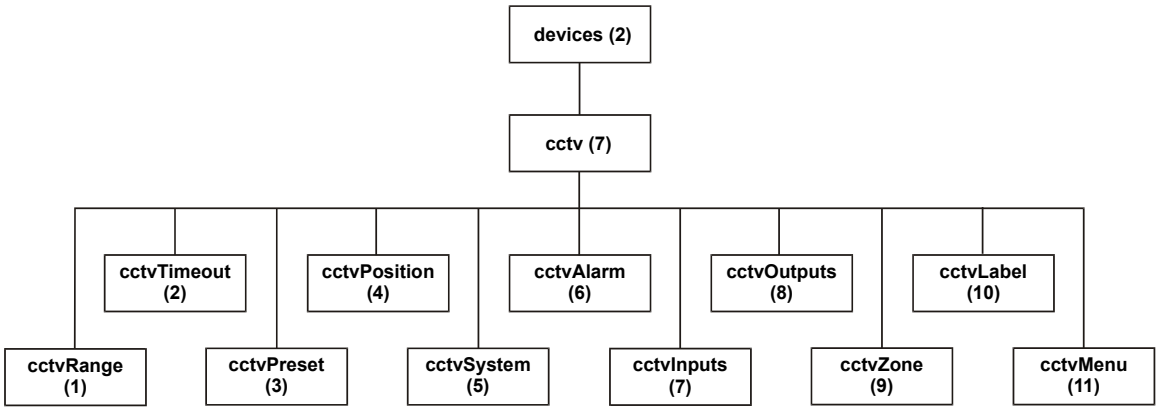
2.5 SUPPLEMENTAL FIGURES

The following two figures provide a pictorial representation of the CCTV Camera Control architecture and the Closed Circuit Television Branch and Tree Structure. This is an architecture that is a proposed component for the National ITS Architecture. The architecture diagram identifies some of the terms and acronyms described above, in addition to identifying the focus of this standard. The tree structure identifies how the object definitions are combined under specific nodes.



Architectural Terminology Diagram

Closed Circuit Television Branch and Tree Structure



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Section 3
CCTV MIB

This section defines those objects that are expected to be used by closed circuit television (CCTV) camera control. The objects are described in terms of the ASN.1 (defined in ISO/IEC 8824-1, ISO/IEC 8824-2, ISO/IEC 8824-3, and ISO/IEC 8824-4) macro OBJECT-TYPE. The OBJECT-TYPE macro is defined in RFC 1212. The text provided from Clause 3.1 through the end of the section (except the clause headings) constitutes the NTCIP Standard CCTV Camera Control MIB.

The clauses below present the objects in lexigraphical order of their OBJECT IDENTIFIERS that correspond to their physical location within the global naming tree. The objects defined in this document reside under the "cctv" node of the global naming tree. To aid in object management, the "cctv" node has been subdivided into logical categories, each defined by a node under the "cctv" node. The individual objects are then located under the appropriate node.

Nodes should not be confused with conformance groups, which are defined in Section 4. A conformance group is a logical grouping of objects that is used for conformance statements. While conformance groups will frequently correspond to the nodal structure, a conformance group may contain objects that are not lexigraphically ordered.

3.1 CLOSED CIRCUIT TELEVISION (CCTV) OBJECTS

```
CCTV-MIB1 DEFINITIONS ::= BEGIN

-- the following OBJECT IDENTIFIERS are used in the CCTV MIB:

IMPORTS
    OBJECT-TYPE
        FROM RFC-1212
    profiles, devices
        FROM TMIB-II;

PositionReference ::= OCTET STRING (SIZE (0..4))
-- PositionReference consists of those parameters required to a four (4) byte octet string.  The value of
-- the first byte determines the interpretation of the subsequent three bytes.
-- control the detailed movement of the camera.  It is defined by an
--aligned OER encoded value of the following structure:
--
-- CHOICE {
-- mode                 OCTET STRING (SIZE (1))
-- Byte 1               Value
-- 00                   stopMovement
-- 01                   delta
-- 10                   absolute
-- 11                   continuous
--
-- SpeedOffset ::= SEQUENCE {
-- speed                INTEGER (-127..127),
--Byte 2                Value
-- stopMovement         INTEGER (0) – stop movement,
-- delta                INTEGER (-127..127) – the value of the speed of movement where larger values
```

denote increasing speed and the sign indicates direction of movement,
-- absolute INTEGER (-127..127) – the value of the speed of movement where larger values
-- denote increasing speed and the sign for the direction of movement is
-- ignored,
-- continuous INTEGER (-127..127) – the value of the speed of movement where larger values
-- denote increasing speed and the sign indicates direction of movement.
--
-- offset INTEGER (0..65535)}
-- Byte 3 and Byte 4 Value
-- stopMovement not used,
-- delta offset from the current position,
-- absolute offset from the Home Position,
-- continuous not used
--
~~-- stopMovement INTEGER (0) -- stop movement,~~
~~-- delta SpeedOffset,~~
~~-- absolute SpeedOffset,~~
~~-- continuous INTEGER (-127..127) -- scalar values of the speed of movement where larger values denote increasing speed}~~

--
-- 'stopMovement' means to stop any choice of movement.
--
-- 'delta' means to move to the specified offset as referenced from the current position. For offsets
-- yielding values beyond the limits, the device moves to the limit and stops.
--
-- 'absolute' means a movement to an absolute position value measured from the Home Position, with
-- movement taking the shortest allowable path and ignoring the indication for direction of movement in
-- Byte 2 (speed).
--
-- 'continuous' means to start moving and continue to move until another movement command is issued,
-- or the device times out.
--
-- Variable speed is not required to be supported. If variable speed is supported, then speeds of -1 and
+1
-- are the slowest speed and speeds of -127 and 127 are the fastest speeds.
--
-- Positive (+) and negative (-) define direction of movement in Byte 2 (speed), except for the 'absolute'
-- mode choice of movement.

-- For the purpose of this section, the following OBJECT IDENTIFIERS are used:
cctv OBJECT IDENTIFIER ::= {devices 7}

3.2 CCTV RANGE OBJECTS

cctvRange OBJECT IDENTIFIER ::= { cctv 1 }

3.2.1 Maximum Number of Presets Parameter

rangeMaximumPreset OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-only
STATUS mandatory
DESCRIPTION "A preset is the pre-specified position where a camera is pointed to a fixed point in space (includes positions for pan, tilt, and zoom). The maximumPreset is a number indicating the total number of possible preset positions supported by the device. A value of zero (0) identifies that the device does not support presets."

::= { cctvRange 1}

3.2.2 Pan Left Limit Parameter

rangePanLeftLimit OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "Specifies the panning left range limit in 1/100th degree units in a clockwise direction from the Home Position. If the rangePanLeftLimit and the rangePanRightLimit are both zero (0), then the device does not support panning movement. If the rangePanLeftLimit and the rangePanRightLimit are both 65535, then the device does not support the concept of right and left limits."
::= { cctvRange 2}

3.2.3 Pan Right Limit Parameter

rangePanRightLimit OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "Specifies the panning right range limit in 1/100th degree units in a clockwise direction from the Home Position. If the rangePanLeftLimit and the rangePanRightLimit are both zero (0), then the device does not support panning movement. If the rangePanLeftLimit and the rangePanRightLimit are both 65535, then the device does not support the concept of right and left limits."
::= { cctvRange 3}

3.2.4 Pan Home Position Parameter

rangePanHomePosition OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "Specifies an arbitrary point on a circle from which the left and right limits are measured in 1/100th degree units. The value of 65535 means that Home position referencing is not supported for the horizontal plane~~.~~."
::= { cctvRange 4}

3.2.5 True North Offset Parameter

rangeTrueNorthOffset OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS read-write
STATUS mandatory
DESCRIPTION "Specifies the offset ~~between~~ from the Home Position to ~~t~~True North in a clockwise direction ~~and the Home Position~~ in 1/100th degree units. When read, this object returns last value written. If the Home Position is true North, then set this value to zero (0). The value of 65535 means that a true North offset from the Home position is not supported. The actual direction of true North is not defined by this standard. True North offset can be used to create an arbitrary coordinate reference position."
::= { cctvRange 5}

3.2.6 Tilt Up Limit Parameter

rangeTiltUpLimit OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)

ACCESS read-only
STATUS mandatory
DESCRIPTION "Specifies the tilting up range limit in 1/100th degree units. The zero point for measurement is any point on horizontal plane ~~the horizon line~~. The horizontal plane is orthogonal to the vertical line extending from the camera's movement point and the center of the earth. The horizontal plane is through the camera's movement point. Tilting upward indicates a positive direction. If the rangeTiltUpLimit and the rangeTiltDownLimit are both zero (0), then the device does not support tilting movement. If the rangeTiltUpLimit and the rangeTiltDownLimit are both 65535, then the device does not support the concept of up and down limits."
::= { cctvRange 6}

3.2.7 Tilt Down Limit Parameter

rangeTiltDownLimit OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "Specifies the tilting down range limit in 1/100th degree units. The zero point for measurement is any point on horizontal plane ~~the horizon line~~. The horizontal plane is orthogonal to the vertical line extending from the camera's movement point and the center of the earth. The horizontal plane is through the camera's movement point. Tilting upward indicates a positive direction. If the rangeTiltUpLimit and the rangeTiltDownLimit are both zero (0), then the device does not support tilting movement. If the rangeTiltUpLimit and the rangeTiltDownLimit are both 65535, then the device does not support the concept of up and down limits."
::= { cctvRange 7}

3.2.8 Zoom Limit Parameter

rangeZoomLimit OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "Specifies the zoom range in arbitrary units. Used for absolute or offset control. Zero (0) identifies that zoom limits are not supported. This number represents the scalar zoom positioning beginning with ~~zero (0)~~ one (1) for wide and ending with 65535 for telephoto."
::= { cctvRange 8}

3.2.9 Focus Limit Parameter

rangeFocusLimit OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "Specifies the focus range in arbitrary units. Used for absolute or offset control. Zero (0) identifies that focus limits are not supported. This number represents the scalar focus positioning beginning with ~~zero (0)~~ one (1) for near and ending with 65535 for far."
::= { cctvRange 9}

3.2.10 Iris Limit Parameter

rangeIrisLimit OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-only
STATUS mandatory

DESCRIPTION "Specifies the iris range in arbitrary units. Used for absolute or offset control. Zero (0) identifies that iris limits are not supported. This number represents the scalar zoom positioning beginning with ~~zero (0)~~ one (1) for open and ending with 65535 for closed. Open is defined as the largest aperture setting. Closed is defined as the smallest aperture setting."
::= { cctvRange 10}

3.2.11 ~~Maximum~~ Minimum Pan Step Angle Parameter

rangeMinimumPanStepAngle OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "Specifies the minimum incremental angle in 1/100th degree units for the minimum pan step size to guarantee movement in the horizontal plane. A value of 65535 means that ~~M~~minimum pan step angle is not supported."
::= { cctvRange 11}

3.2.12 ~~Maximum~~ Minimum Tilt Step Angle Parameter

rangeMinimumTiltStepAngle OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "Specifies the minimum incremental angle in 1/100th degree units for the minimum tilt step size to guarantee movement in the vertical plane. A value of 65535 means that minimum tilt step angle is not supported."
::= { cctvRange 12}

3.3 CCTV TIMEOUT OBJECTS

cctvTimeout OBJECT IDENTIFIER ::= { cctv 2 }

3.3.1 Pan Timeout Parameter

timeoutPan OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-write
STATUS mandatory
DESCRIPTION "A number indicating the total number of milliseconds that a panning motion can continue without ~~a~~ the reissue of a pan command. A value of zero (0) identifies that panning timeout is not supported."
::= {cctvTimeout 1}

3.3.2 Tilt Timeout Parameter

timeoutTilt OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-write
STATUS mandatory
DESCRIPTION "A number indicating the total number of milliseconds that a tilting motion can continue without ~~a~~ the reissue of a tilt command. A value of zero (0) identifies that tilting timeout is not supported."
::= {cctvTimeout 2}

3.3.3 Zoom Timeout Parameter

timeoutZoom OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-write
STATUS mandatory
DESCRIPTION "A number indicating the total number of milliseconds that a zoom motion can continue without ~~a~~ the reissue of a zoom command. A value of zero (0) identifies that zooming timeout is not supported."
::= {cctvTimeout 3}

3.3.4 Focus Timeout Parameter

timeoutFocus OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-write
STATUS mandatory
DESCRIPTION "A number indicating the total number of milliseconds that a focus motion can continue without ~~a~~ the reissue of a focus type command. A value of zero (0) identifies that focusing timeout is not supported."
::= {cctvTimeout 4}

3.3.5 Iris Timeout Parameter

timeoutIris OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-write
STATUS mandatory
DESCRIPTION "A number indicating the total number of milliseconds that an iris motion can continue without ~~a~~ the reissue of a iris type command. A value of zero (0) identifies that iris timeout is not supported."
::= {cctvTimeout 5}

3.4 CCTV PRESET OBJECTS

cctvPreset OBJECT IDENTIFIER ::= { cctv 3 }

3.4.1 Go To Preset Position Parameter

presetGotoPosition OBJECT-TYPE
SYNTAX INTEGER (~~0~~ 1..255)
ACCESS read-write
STATUS mandatory
DESCRIPTION "Writing to this object commands the device to move to a preset if that preset exists. ~~Reading~~ When read, this object returns the last value written. ~~This value is reset to zero (0) upon the issuance of a pan, tilt, or zoom command.~~"
::= {cctvPreset 1}

3.4.2 Store Preset Position Parameter

presetStorePosition OBJECT-TYPE
SYNTAX INTEGER (~~0~~ 1..255)
ACCESS read-write

STATUS mandatory
DESCRIPTION "Writing to this object commands the device to save the current pan, tilt, zoom, and focus positions to the specified preset. ~~Reading~~ When read, this object returns the last value written. ~~This value is reset to zero (0) upon the issuance of a pan, tilt, or zoom command.~~"
::= {cctvPreset 2}

3.4.3 Preset Position Query Parameter

presetPositionQuery OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-only
STATUS mandatory
DESCRIPTION "This object indicates the number of the preset where the device is currently positioned. A value of zero (0) indicates that the device is not currently at a preset position."
::= {cctvPreset 3}

3.5 CCTV POSITIONING OBJECTS

cctvPosition OBJECT IDENTIFIER ::= { cctv 4 }

3.5.1 Pan Position Parameter

positionPan OBJECT-TYPE
SYNTAX PositionReference
ACCESS read-write
STATUS mandatory
DESCRIPTION "Object is 4 bytes in length:
Byte 1 is the mode of operation defined as stop movement, delta, absolute, or continuous movement,
Byte 2 is speed defined as ~~a scalar unit~~ the value of the speed of movement with positive (+) being clockwise and negative (–) being counterclockwise,
Bytes 3 and 4 specify a position or offset measurement in 1/100th degrees.
The minimum amount of movement shall be one step as defined by the rangeMinimumPanStepAngle. The use of absolute in the PositionReference choice is measured from the Home position. When read, this object returns last value written."
::= {cctvPosition 1}

3.5.2 Tilt Position Parameter

positionTilt OBJECT-TYPE
SYNTAX PositionReference
ACCESS read-write
STATUS mandatory
DESCRIPTION "Object is 4 bytes in length:
Byte 1 is the mode of operation defined as stop movement, delta, absolute, or continuous movement,
Byte 2 is speed defined as ~~a scalar unit~~ the value of the speed of movement with positive (+) being up and negative (–) being down,
Bytes 3 and 4 specify a position or offset measurement in 1/100th degrees.
The minimum amount of movement shall be one step as defined by the rangeMinimumTiltStepAngle. When read, this object returns last value written."
::= {cctvPosition 2}

3.5.3 Lens Zoom Position Parameter

positionZoomLens OBJECT-TYPE
SYNTAX PositionReference

ACCESS read-write
STATUS mandatory
DESCRIPTION "Object is 4 bytes in length:
Byte 1 is the mode of operation defined as stop movement, delta, absolute, or continuous movement,
Byte 2 is speed defined as ~~a scalar unit~~ the value of the speed of movement with positive (+) being telephoto and negative (–) being wide,
Bytes 3 and 4 specify a position or offset measurement in scalar linear units with a maximum value of the specified limit.
When read, this object returns last value written."
::= {cctvPosition 3}

3.5.4 Lens Focus Position Parameter

positionFocusLens OBJECT-TYPE
SYNTAX PositionReference
ACCESS read-write
STATUS mandatory
DESCRIPTION "Object is 4 bytes in length:
Byte 1 is the mode of operation defined as stop movement, delta, absolute, or continuous movement,
Byte 2 is speed defined as ~~a scalar unit~~ the value of the speed of movement with positive (+) being far and negative (–) being near,
Bytes 3 and 4 specify a position or offset measurement in scalar units with a maximum value of the specified limit.
When read, this object returns last value written."
::= {cctvPosition 4}

3.5.5 Lens Iris Position Parameter

positionIrisLens OBJECT-TYPE
SYNTAX PositionReference
ACCESS read-write
STATUS mandatory
DESCRIPTION "Object is 4 bytes in length:
Byte 1 is the mode of operation defined as stop movement, delta, absolute, or continuous movement,
Byte 2 is speed defined as ~~a scalar unit~~ the value of the speed of movement with positive (+) being closed and negative (–) being opened,
Bytes 3 and 4 specify a position or offset measurement in scalar units with a maximum value of the specified limit.
When read, this object returns last value written."
::= {cctvPosition 5}

3.5.6 Pan Position Query Parameter

positionQueryPan OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "This object indicates the angle in 1/100th degree units for the current pan position in the horizontal plane, measured in a clockwise direction from the Home position. A value of 65535 indicates that a query of the pan position is not supported."
::= {cctvPosition 6}

3.5.7 Tilt Position Query Parameter

positionQueryTilt OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "This object indicates the angle in 1/100th degree units for the current tilt position in the vertical plane, measured from the horizontal plane. Tilting upward indicates a positive direction. A value of 65535 indicates that a query of the pan position is not supported. This object is always reported as values between 270 degrees to 359.99 degrees and 0 degrees to 90 degrees."
::= {cctvPosition 7}

3.5.8 Zoom Position Query Parameter

positionQueryZoom OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-only
STATUS mandatory
DESCRIPTION "This object indicates the value for the current zoom position, beginning with one (1) for wide and ending with 65535 for telephoto. A value of zero (0) indicates that a query of the zoom position is not supported."
::= {cctvPosition 8}

3.5.9 Focus Position Query Parameter

positionQueryFocus OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-only
STATUS optional
DESCRIPTION "This object indicates the value for the current focus position, beginning with one (1) for near and ending with 65535 for far. A value of zero (0) indicates that a query of the focus position is not supported."
::= {cctvPosition 9}

3.5.10 Iris Position Query Parameter

positionQueryIris OBJECT-TYPE
SYNTAX INTEGER (0..65535)
ACCESS read-only
STATUS optional
DESCRIPTION "This object indicates the value for the current iris position, beginning with one (1) for open and ending with 65535 for closed. A value of zero (0) indicates that a query of the iris position is not supported."
::= {cctvPosition 10}

3.6 CCTV SYSTEM FEATURE CONTROL OBJECTS

cctvSystem OBJECT IDENTIFIER ::= {cctv 5}

3.6.1 System Camera Feature Control Parameter

systemCameraFeatureControl OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(2))
ACCESS read-write
STATUS mandatory
DESCRIPTION "A bit mapped value as defined below:

Byte1
Bit7 0 = OFF, 1 = ON for the selection of Camera Power (MSB),
Bit6 0 = OFF, 1 = ON for the selection of Heater Power,
Bit5 0 = OFF, 1 = ON for the selection of Wiper,
Bit4 0 = OFF, 1 = ON for the selection of Washer,
Bit3 0 = OFF, 1 = ON for the selection of Blower,
Bits2..0 Reserved (Bit0 = LSB),
Byte 2
Bit7 0 = OFF, 1 = ON for activation and deactivation of the camera component (MSB),
Bits6..0 Reserved (Bit0 = LSB).
When read, this object returns last value written."
::= {cctvSystem 1}

3.6.2 System Camera Feature Status

systemCameraFeatureStatus OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-only
STATUS mandatory
DESCRIPTION "A bit mapped value as defined below:
~~Byte1~~
Bit7 0 = OFF, 1 = ON for status of Camera Power (MSB),
Bit6 0 = OFF, 1 = ON for status of Heater Power,
Bit5 0 = OFF, 1 = ON for status of Wiper,
Bit4 0 = OFF, 1 = ON for status of Washer,
Bit3 0 = OFF, 1 = ON for status of Blower,
Bits2..0 Reserved (Bit0 = LSB)~~,~~."
::= {cctvSystem 2}

3.6.3 System Camera Equipment Availability Parameter

systemCameraEquipped OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS ~~read-write~~ read-only
STATUS mandatory
DESCRIPTION "A bit mapped value as defined below:
Bit7 0 = NO, 1 = YES denotes the availability of a controllable Camera Power supply (MSB),
Bit6 0 = NO, 1 = YES denotes the availability of a controllable Heater Power supply,
Bit5 0 = NO, 1 = YES denotes the availability of a controllable Wiper,
Bit4 0 = NO, 1 = YES denotes the availability of a controllable Washer,
Bit3 0 = NO, 1 = YES denotes the availability of a controllable Blower,
Bits2..0 Reserved (Bit0 = LSB).
~~When read, this object returns last value written~~."
::= {cctvSystem 3}

3.6.4 System Lens Feature Control Parameter

systemLensFeatureControl OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(2))
ACCESS read-write
STATUS mandatory
DESCRIPTION "A bit mapped value as defined below:
Byte1

Bit 7 0 = OFF, 1 = ON for the selection of Auto Iris (MSB),
Bit 6 0 = OFF, 1 = ON for the selection of Auto Focus,
Bits5..0 Reserved (Bit 0 = LSB),
Byte2
Bit7 0 = OFF, 1 = ON for activation and deactivation of the lens component (MSB),
Bits6..0 Reserved (Bit0 = LSB).
When read, this object returns last value written."
::= {cctvSystem 4}

3.6.5 System Lens Feature Status Parameter

systemLensFeatureStatus OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS ~~read-write~~ read-only
STATUS mandatory
DESCRIPTION "A bit mapped value as defined below:
Bit 7 0 = OFF, 1 = ON for Auto Iris status (MSB),
Bit 6 0 = OFF, 1 = ON for Auto Focus status,
Bits5..0 Reserved (Bit 0 = LSB)~~.~~."
::= {cctvSystem 5}

3.6.6 System Lens Equipment Availability Parameter

systemLensEquipped OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS ~~read-write~~ read-only
STATUS mandatory
DESCRIPTION "A bit mapped value as defined below:
Bit 7 0 = NO, 1 = YES denotes the availability of a controllable Auto Iris (MSB),
Bit 6 0 = NO, 1 = YES denotes the availability of a controllable Auto Focus,
Bits5..0 Reserved (Bit 0 = LSB)."
::= {cctvSystem 6}

3.7 CCTV ALARM OBJECTS

cctvAlarm OBJECT IDENTIFIER ::= { cctv 6 }

3.7.1 Alarm Status Parameter

alarmStatus OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-only
STATUS mandatory
DESCRIPTION "Alarm status denotes a bit mapped value that indicates the current status of alarms, as outlined below:
Bit7 0 = OFF, 1 = ON for the active status of the Cabinet Alarm signifying cabinet entry (MSB),
Bit6 0 = OFF, 1 = ON for the active status of the Enclosure Alarm signifying enclosure entry,
Bit5 0 = OFF, 1 = ON for the active status of the Video Loss Alarm signifying presence of video sync,
Bit4 0 = OFF, 1 = ON for the active status of the Temperature Alarm signifying a value outside the allowable threshold range for internal camera enclosure temperature,

Bit3 0 = OFF, 1 = ON for the active status of the Pressure Alarm signifying a current value outside the allowable threshold range for the internal camera enclosure pressure,
Bit2 0 = Local, 1 = Remote for the active status of the Local/Remote Alarm,
Bit1 0 = OFF, 1 = ON for the active status of the Washer Fluid Alarm signifying a current value outside the allowable threshold range for the washer fluid capacity,
Bit0 Reserved (LSB)."
::= {cctvAlarm 1}

3.7.2 Alarm Latch Status Parameter

alarmLatchStatus OBJECT-TYPE
SYNTAX OCTET STRING (SIZE (1))
ACCESS read-only
STATUS mandatory
DESCRIPTION "Latch status denotes a bit mapped value that indicates the presence of a latched alarm, indicating that an alarm has occurred since the previous latch was cleared, as outlined below:
Bit7 0 = OFF, 1 = ON for the latch status of the Cabinet Alarm (MSB),
Bit6 0 = OFF, 1 = ON for the latch status of the Enclosure Alarm,
Bit5 0 = OFF, 1 = ON for the latch status of the Video Loss Alarm,
Bit4 0 = OFF, 1 = ON for the latch status of the Temperature Alarm,
Bit3 0 = OFF, 1 = ON for the latch status of the Pressure Alarm,
Bit2 0 = Local, 1 = Remote for the latch status of the Local/Remote Alarm,
Bit1 0 = OFF, 1 = ON for the latch status of the Washer Fluid Alarm,
Bit0 Reserved (LSB)."
::= {cctvAlarm 2}

3.7.3 Alarm Latch Clear Parameter

alarmLatchClear OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Latch clear denotes a bit mapped value that clears the presence of a latched alarm, as outlined below:
Bit7 0 = OFF, 1 = ON for clearing the alarm latch for the Cabinet Alarm (MSB),
Bit6 0 = OFF, 1 = ON for clearing the alarm latch for the Enclosure Alarm,
Bit5 0 = OFF, 1 = ON for clearing the alarm latch for the Video Loss Alarm,
Bit4 0 = OFF, 1 = ON for clearing the alarm latch for the Temperature Alarm,
Bit3 0 = OFF, 1 = ON for clearing the alarm latch for the Pressure Alarm,
Bit2 0 = Local, 1 = Remote for clearing the alarm latch for the Local/Remote Alarm,
Bit1 0 = OFF, 1 = ON for clearing the alarm latch for the Washer Fluid Alarm,
Bit0 Reserved (LSB).
When read, the value of this object returns the last value written until the latched is cleared and then zero (0) for each bit position."
::= {cctvAlarm 3}

3.7.4 Temperature Alarm High-Low Threshold

alarmTemperatureHighLowThreshold OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(2))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Identifies the high and low thresholds for the temperature alarm, as shown below;
Byte1 Low Threshold denotes the value of minimum internal camera enclosure

temperature measured in degrees C,
Byte2 HighThreshold denotes the value of maximum internal camera enclosure temperature measured in degrees C.
When read, this object returns the last value written."
::= {cctvAlarm 4}

3.7.5 Temperature Alarm Current Value Parameter

alarmTemperatureCurrentValue OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS ~~read-write~~ read-only
STATUS mandatory
DESCRIPTION "Identifies the current value for the temperature within the camera enclosure measured in degrees C."
::= {cctvAlarm 5}

3.7.6 Pressure Alarm High-Low Threshold Parameter

alarmPressureHighLowThreshold OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(2))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Identifies the high and low thresholds for the pressure alarm, as shown below;
Byte1 Low Threshold denotes the value of minimum pressure within the camera enclosure measured in psig,
Byte2 HighThreshold denotes the value of maximum pressure within the camera enclosure measured in psig.
When read, this object returns the last value written."
::= {cctvAlarm 6}

3.7.7 Pressure Alarm Current Value Parameter

alarmPressureCurrentValue OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS ~~read-write~~ read-only
STATUS mandatory
DESCRIPTION "Identifies the current value for the pressure within the camera enclosure measured in psig."
::= {cctvAlarm 7}

3.7.8 Washer Fluid Alarm High-Low Threshold Parameter

alarmWasherFluidHighLowThreshold OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(2))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Identifies the high and low thresholds for the washer fluid alarm, as shown below;
Byte1 Low Threshold denotes the percentage of minimum filled capacity between zero (0) and 100 percent,
Byte2 HighThreshold denotes the percentage of maximum filled capacity between zero (0) and 100 percent."
::= {cctvAlarm 8}

3.7.9 Washer Fluid Alarm Current Value Parameter

alarmWasherFluidCurrentValue OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS ~~read-write~~ read-only
STATUS mandatory
DESCRIPTION "Identifies the current value for the washer fluid level measured as the amount of filled capacity between zero (0) and 100 percent."
::= {cctvAlarm 9}

3.7.10 Alarm Label Index Parameter

alarmLabelIndex OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(7))
ACCESS ~~read-only~~ read-write
STATUS mandatory
DESCRIPTION "The label number identifies the entry into the camera control label table that provides additional text information or on-screen text information. Labels are text strings with formatting, positioning, and display information. Labels are displayed while the alarm status is ON. A value of zero (0) indicates that there is no camera control label table entry for the alarm. The alarms are identified below:

Byte1	for the Cabinet Alarm label number,
Byte2	for the Enclosure Alarm label number,
Byte3	for the Video Loss Alarm label number,
Byte4	for the Temperature Alarm label number,
Byte5	for the Pressure Alarm label number,
Byte6	for the Local/Remote Alarm label number,
Byte7	for the Washer Fluid Alarm label number.

When read, return the last value written."
::= {cctvAlarm 10}

3.7.11 Alarm Label Source Parameter

alarmLabelSource OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Designates the source of the alarm label as being displayed upon the current status of the alarm as indicated by the alarmStatus parameter or continuously displayed during the presence of a latched alarm as indicated by the alarmLatchStatus. The command for designating the alarm label source is as follows:

Bit7	0 = Status, 1 = LatchedStatus for the Cabinet Alarm (MSB),
Bit6	0 = Status, 1 = LatchedStatus for the Enclosure Alarm,
Bit5	0 = Status, 1 = LatchedStatus for the Video Loss Alarm,
Bit4	0 = Status, 1 = LatchedStatus for the Temperature Alarm,
Bit3	0 = Status, 1 = LatchedStatus for the Pressure Alarm,
Bit2	0 = Status, 1 = LatchedStatus for the Local/Remote Alarm,
Bit1	0 = Status, 1 = LatchedStatus for the Washer Fluid Alarm,
Bit0	Reserved (LSB).

When read, this object returns the last value written."
::= {cctvAlarm 11}

3.8 CCTV DISCRETE INPUT OBJECTS

cctvInput OBJECT IDENTIFIER ::= { cctv 7 }

3.8.1 Discrete Input Status Parameter

inputStatus OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-only
STATUS mandatory
DESCRIPTION "Input status denotes a bit mapped value that indicates the current state of eight (8) user defined discrete inputs, as outlined below:

Bit7	0 = OFF, 1 = ON for the active status of discrete Input 8 (MSB),
Bit6	0 = OFF, 1 = ON for the active status of discrete Input 7,
Bit5	0 = OFF, 1 = ON for the active status of discrete Input 6,
Bit4	0 = OFF, 1 = ON for the active status of discrete Input 5,
Bit3	0 = OFF, 1 = ON for the active status of discrete Input 4,
Bit2	0 = OFF, 1 = ON for the active status of discrete Input 3,
Bit1	0 = OFF, 1 = ON for the active status of discrete Input 2,
Bit0	0 = OFF, 1 = ON for the active status of discrete Input 1 (LSB).

Please note that user defined discrete inputs may reduce interoperability of the device."
::= {cctvInput 1}

3.8.2 Discrete Input Latch Status Parameter

inputLatchStatus OBJECT-TYPE
SYNTAX OCTET STRING (SIZE (1))
ACCESS read-only
STATUS mandatory
DESCRIPTION "Latch status denotes a bit mapped value that indicates the presence of a latched input for eight (8) user defined discrete inputs, indicating that an input has occurred since the previous latch was cleared, as outlined below:

Bit7	0 = OFF, 1 = ON for the latch status of the discrete Input 8 (MSB),
Bit6	0 = OFF, 1 = ON for the latch status of the discrete Input 7,
Bit5	0 = OFF, 1 = ON for the latch status of the discrete Input 6,
Bit4	0 = OFF, 1 = ON for the latch status of the discrete Input 5,
Bit3	0 = OFF, 1 = ON for the latch status of the discrete Input 4,
Bit2	0 = OFF, 1 = ON for the latch status of the discrete Input 3,
Bit1	0 = OFF, 1 = ON for the latch status of the discrete Input 2,
Bit0	0 = OFF, 1 = ON for the latch status of the discrete Input 1 (LSB).

Please note that user defined discrete inputs may reduce interoperability of the device."
::= {cctvInput 2}

3.8.3 Discrete Input Latch Clear Parameter

inputLatchClear OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Latch clear denotes a bit mapped value that clears the presence of a latched input for eight (8) user defined discrete inputs, as outlined below:

Bit7	0 = OFF, 1 = ON for clearing the input latch for discrete Input 8 (MSB),
Bit6	0 = OFF, 1 = ON for clearing the input latch for discrete Input 7,
Bit5	0 = OFF, 1 = ON for clearing the input latch for discrete Input 6,
Bit4	0 = OFF, 1 = ON for clearing the input latch for discrete Input 5,
Bit3	0 = OFF, 1 = ON for clearing the input latch for discrete Input 4,
Bit2	0 = OFF, 1 = ON for clearing the input latch for discrete Input 3,
Bit1	0 = OFF, 1 = ON for clearing the input latch for discrete Input 2,

Bit0 0 = OFF, 1 = ON for clearing the input latch for discrete Input 1 (LSB).
When read, the value of this object returns the last value written until the latched is cleared and then zero (0) for each bit position. Please note that user defined discrete inputs may reduce interoperability of the device."
::= {cctvInput 3}

3.8.4 Discrete Input Label Index Parameter

inputLabelIndex OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(8))
ACCESS ~~read-only~~ read-write
STATUS mandatory
DESCRIPTION "The label number identifies the entry into the camera control label table that provides additional text information or on-screen text information. Labels are text strings with formatting, positioning, and display information. Labels are displayed while the input latch status is ON. A value of zero (0) indicates that there is no camera control label table entry for the input. The user defined discrete inputs are identified below:

Byte1	for the discrete Input 1 label number (MSB),
Byte2	for the discrete Input 2 label number,
Byte3	for the discrete Input 3 label number,
Byte4	for the discrete Input 4 label number,
Byte5	for the discrete Input 5 label number,
Byte6	for the discrete Input 6 label number,
Byte7	for the discrete Input 7 label number,
Byte8	for the discrete Input 8 label number (LSB)."

::= {cctvInput 4}

3.8.5 Discrete Input Preset Index Parameter

inputPresetIndex OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(8))
ACCESS read-write
STATUS mandatory
DESCRIPTION "The preset index denotes a bit-mapped value representing the preset to which the device is commanded to move to upon the active status of a discrete input as indicated by the inputStatus parameter. A value of zero (0) indicates that there is no preset for the input. The user defined discrete inputs are identified below:

Byte1	for the discrete Input 1 preset number (MSB),
Byte2	for the discrete Input 2 preset number,
Byte3	for the discrete Input 3 preset number,
Byte4	for the discrete Input 4 preset number,
Byte5	for the discrete Input 5 preset number,
Byte6	for the discrete Input 6 preset number,
Byte7	for the discrete Input 7 preset number,
Byte8	for the discrete Input 8 preset number (LSB).

When read, this object returns the last value written."
::= {cctvInput 5}

3.8.6 Input Label Source Parameter

inputLabelSource OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Designates the source of the input label as being displayed upon the current status of

the input as indicated by the inputStatus parameter or continuously displayed during the presence of a latched input as indicated by the inputLatchStatus. The command for designating the input label source is as follows:

Bit7 0 = Status, 1 = LatchedStatus for discrete Input 8 (MSB),
Bit6 0 = Status, 1 = LatchedStatus for discrete Input 7,
Bit5 0 = Status, 1 = LatchedStatus for discrete Input 6,
Bit4 0 = Status, 1 = LatchedStatus for discrete Input 5,
Bit3 0 = Status, 1 = LatchedStatus for discrete Input 4,
Bit2 0 = Status, 1 = LatchedStatus for discrete Input 3,
Bit1 0 = Status, 1 = LatchedStatus for discrete Input 2,
Bit0 0 = Status, 1 = LatchedStatus for discrete Input 1 (LSB).

When read, this object returns the last value written."
::= {cctvInput 6}

3.9 CCTV DISCRETE OUTPUT OBJECTS

cctvOutput OBJECT IDENTIFIER ::= { cctv 8 }

3.9.1 Discrete Output Status Parameter

outputStatus OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-only
STATUS mandatory
DESCRIPTION "Output status denotes a bit mapped value that indicates the current state of eight (8) user defined discrete outputs, as outlined below:

Bit7 0 = OFF, 1 = ON for the active status of discrete Output 8 (MSB),
Bit6 0 = OFF, 1 = ON for the active status of discrete Output 7,
Bit5 0 = OFF, 1 = ON for the active status of discrete Output 6,
Bit4 0 = OFF, 1 = ON for the active status of discrete Output 5,
Bit3 0 = OFF, 1 = ON for the active status of discrete Output 4,
Bit2 0 = OFF, 1 = ON for the active status of discrete Output 3,
Bit1 0 = OFF, 1 = ON for the active status of discrete Output 2,
Bit0 0 = OFF, 1 = ON for the active status of discrete Output 1 (LSB).

Please note that user defined discrete outputs may reduce interoperability of the device."
::= {cctvOutput 1}

3.9.2 Discrete Output Control Parameter

outputControl OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(2))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Output control activates and deactivates individual user defined discrete outputs as outlined below:

~~Byte1 discrete Output number to be controlled, 1 through 8,~~
~~Byte2~~

~~Bit7 0 = OFF, 1 = ON for the active status of discrete Output (MSB),~~
~~Bits6..0 reserved (Bit 0 = LSB).~~

Byte1

Bit7 0 = NOT SELECT, 1 = SELECT designates the control of Output 8 (MSB),
Bit6 0 = NOT SELECT, 1 = SELECT designates the control of Output 7,
Bit5 0 = NOT SELECT, 1 = SELECT designates the control of Output 6,
Bit4 0 = NOT SELECT, 1 = SELECT designates the control of Output 5,

Bit3 0 = NOT SELECT, 1 = SELECT designates the control of Output 4,
Bit2 0 = NOT SELECT, 1 = SELECT designates the control of Output 3,
Bit1 0 = NOT SELECT, 1 = SELECT designates the control of Output 2,
Bit0 0 = NOT SELECT, 1 = SELECT designates the control of Output 1(LSB),
Byte2
Bit7 0 = OFF, 1 = ON for the desired active state of discrete Output 8(MSB),
Bit6 0 = OFF, 1 = ON for the desired active state of discrete Output 7,
Bit5 0 = OFF, 1 = ON for the desired active state of discrete Output 6,
Bit4 0 = OFF, 1 = ON for the desired active state of discrete Output 5,
Bit3 0 = OFF, 1 = ON for the desired active state of discrete Output 4,
Bit2 0 = OFF, 1 = ON for the desired active state of discrete Output 3,
Bit1 0 = OFF, 1 = ON for the desired active state of discrete Output 2,
Bit0 0 = OFF, 1 = ON for the desired active state of discrete Output 1(LSB).
Please note that user defined discrete outputs may reduce interoperability of the device."
::= {cctvOutput 2}

3.9.3 Discrete Output Label Index

outputLabelIndex OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(8))
ACCESS ~~read-only~~ read-write
STATUS mandatory
DESCRIPTION "The label number identifies the entry into the camera control label table that provides additional text information or on-screen text information. Labels are text strings with formatting, positioning, and display information. A value of zero (0) indicates that there is no camera control label table entry for the input. The user defined discrete outputs are identified below:
Byte1 for the discrete Output 1 label number,
Byte2 for the discrete Output 2 label number,
Byte3 for the discrete Output 3 label number,
Byte4 for the discrete Output 4 label number,
Byte5 for the discrete Output 5 label number,
Byte6 for the discrete Output 6 label number,
Byte7 for the discrete Output 7 label number,
Byte8 for the discrete Output 8 label number."
::= {cctvOutput 3}

3.10 CCTV ZONE OBJECTS

cctvZone OBJECT IDENTIFIER ::= { cctv 9 }

3.10.1 Maximum Number of Zones Parameter

zoneMaximum OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS ~~read-write~~ read-only
STATUS mandatory
DESCRIPTION "Defines the maximum number of zones for this device. A zone is a region in space defined by pan and tilt limits. ~~When read, this object returns last value written~~."
::= {cctvZone 1}

3.10.2 Zone Table

zoneTable OBJECT-TYPE
SYNTAX SEQUENCE OF ZoneEntry

ACCESS not-accessible
STATUS mandatory
DESCRIPTION "A table containing information about zones. Each row in the table identifies a single zone. A zone is a region in space defined by pan and tilt limits."
::= {cctvZone 2}

zoneEntry OBJECT-TYPE
SYNTAX ZoneEntry
ACCESS not-accessible
STATUS mandatory
DESCRIPTION "Parameters of the zone table."
INDEX {zoneIndex}
::= {zoneTable 1}

ZoneEntry ::= SEQUENCE {
zoneIndex INTEGER,
zoneLabel INTEGER,
zonePanLeftLimit INTEGER,
zonePanRightLimit INTEGER,
zoneTiltUpLimit INTEGER,
zoneTiltDownLimit INTEGER,
zoneVideoControl OCTET STRING
}

3.10.2.1 Zone Index Parameter

zoneIndex OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-only
STATUS mandatory
DESCRIPTION "The number associated with each individual zone. A zone is a region in space defined by pan and tilt limits."
::= {zoneEntry 1}

3.10.2.2 Zone Label Parameter

zoneLabel OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-write
STATUS mandatory
DESCRIPTION "Defines the label ~~number~~ index from the camera control label table that is associated with this zone number. When the camera enters the zone, the label text associated with the label index is displayed. If zones overlap, at least one label will be displayed in the overlapped area. A value of zero (0) means that no label is associated with this zone. When read, this object returns the last value written."
::= {zoneEntry 2}

3.10.2.3 Zone Pan Left Limit Parameter

zonePanLeftLimit OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS ~~read-only~~ read-write
STATUS mandatory
DESCRIPTION "Specifies the panning left zone limit in 1/100th degree units in a clockwise direction from the Home Position. The value of 65535 means that a pan left limit is not supported. When read, this

object returns the last value written."
::= { zoneEntry 3}

3.10.2.4 Zone Pan Right Limit Parameter

zonePanRightLimit OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS ~~read-only~~ read-write
STATUS mandatory
DESCRIPTION "Specifies the panning right zone limit in 1/100th degree units in a clockwise direction from the Home Position. The value of 65535 means that a pan right limit is not supported. When read, this object returns the last value written."
::= { zoneEntry 4}

3.10.2.5 Zone Tilt Up Limit Parameter

zoneTiltUpLimit OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS ~~read-only~~ read-write
STATUS mandatory
DESCRIPTION "Specifies the tilting up zone limit in 1/100th degree units. The zero point for measurement is the ~~horizon line~~ horizontal plane. The value of 65535 means that a tilt up limit is not supported. When read, this object returns the last value written."
::= { zoneEntry 5}

3.10.2.6 Zone Tilt Down Limit Parameter

zoneTiltDownLimit OBJECT-TYPE
SYNTAX INTEGER (0..35999 | 65535)
ACCESS ~~read-only~~ read-write
STATUS mandatory
DESCRIPTION "Specifies the tilting down zone limit in 1/100th degree units. The zero point for measurement is the ~~horizon line~~ horizontal plane. The value of 65535 means that a tilt down limit is not supported. When read, this object returns the last value written."
::= { zoneEntry 6}

3.10.2.7 Zone Video Control Parameter

zoneVideoControl OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Denotes a bit mapped value that commands the device to turn the video signal output OFF upon entering a zone. The default video signal shall be ON. The command for video control within a zone is as follows:

Bit 7	0 = OFF, 1 = ON for controlling video signal output from the camera within a zone (MSB),
Bits6..0	Reserved (Bit 0 = LSB).

When read, this object returns the last value written."
::= {zoneEntry 7}

3.10.3 Camera Zone Functions Availability Parameter

zoneCameraEquipped OBJECT-TYPE


```
SYNTAX          OCTET STRING (SIZE(1))
ACCESS          read-only
STATUS          mandatory
DESCRIPTION "A bit mapped value as defined below:
        Bit7            0 = NO, 1 = YES denotes the availability of zones (MSB),
        Bit6            0 = NO, 1 = YES denotes the availability of zone labels,
        Bit5            0 = NO, 1 = YES denotes the availability of the control of video signal within a
                        zone,
        Bits4..0        Reserved (Bit0 = LSB)."
::= {cctvZone 3}
```

3.11 CCTV LABEL OBJECTS

```
cctvLabel       OBJECT IDENTIFIER ::= { cctv 10 }
```

3.11.1 Maximum Number of Labels Parameter

```
labelMaximum    OBJECT-TYPE
SYNTAX          INTEGER (0..255)
ACCESS          read-write read-only
STATUS          mandatory
DESCRIPTION "Defines the maximum number of labels in the camera control label table.  A label is
defined as text with position, font, and color information.  When read, returns last value written."
::= {cctvLabel 1}
```

3.11.2 Label Table

```
labelTable      OBJECT-TYPE
SYNTAX          SEQUENCE OF LabelEntry
ACCESS          not-accessible
STATUS          mandatory
DESCRIPTION “This table contains data specific to each label.  A label is defined as text with position,
font, and color information. Each row in the table identifies a single label."
::= {cctvLabel 2}

labelEntry      OBJECT-TYPE
SYNTAX          LabelEntry
ACCESS          not-accessible
STATUS          mandatory
DESCRIPTION “Parameters of the camera control label table."
INDEX {labelIndex}
::= {labelTable 1}

LabelEntry ::= SEQUENCE {
        labelIndex              INTEGER,
        labelText               OCTET STRING,
        labelFontType           INTEGER,
        labelHeight             INTEGER,
        labelColor              INTEGER,
        labelStartRow           INTEGER,
        labelStartColumn        INTEGER,
        labelStatus             OCTET STRING,
        labelActive             OCTET STRING,
        labelFontNumber         INTEGER
```


}

3.11.2.1 Label Index Parameter

labelIndex OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-only
STATUS mandatory
DESCRIPTION "The number associated with each individual label."
::= { labelEntry 1}

3.11.2.2 Label Text Parameter

labelText OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(0..255))
ACCESS read-write
STATUS mandatory
DESCRIPTION "Text for the label. The label text must fit within the frame-size available for the application."
::= { labelEntry 2}

3.11.2.3 Label Font Type Parameter

labelFontType OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-write
STATUS ~~mandatory~~ deprecated
DESCRIPTION "Designates the ~~type~~ style of font to be displayed. The ASCII font style must be supported ~~Only one font style may be supported~~ and that font style is taken to be the default style.

Value	Meaning
1	designates ASCII text characters to be displayed,
2	designates Bit Mapped Characters to be displayed."

::= { labelEntry 3}

3.11.2.4 Label Height Parameter

labelHeight OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-write
STATUS mandatory
DESCRIPTION "Height of this label text represented as a percent of screen filled by the text and scaled to a range of zero (0) and 255 to fit the height of screen. A height of zero (0) indicates that a label is not displayed and a height of 255 indicates that the label is presented at a maximum height. If the requested label height cannot be supported then the nearest label height will be used. When read, the actual label height implemented will be returned."
::= { labelEntry 4}

3.11.2.5 Label Color Parameter

labelColor OBJECT-TYPE
SYNTAX INTEGER {
blue(1),
green(2),
cyan(3),

red(4),
magenta(5),
brown(6),
white(7),
grey(8),
lightBlue(9),
lightGreen(10),
lightCyan(11),
lightRed(12),
lightMagenta(13),
yellow(14),
brightWhite(15),
black(16)}

ACCESS read-write
STATUS mandatory
DESCRIPTION "Color of the label characters. The default color of white must always be supported. The color is defined as follows:

Value	Meaning
1	blue,
2	green,
3	cyan,
4	red,
5	magenta,
6	brown,
7	white,
8	grey,
9	lightBlue,
10	lightGreen,
11	lightCyan,
12	lightRed,
13	lightMagenta,
14	yellow,
15	brightWhite,
16	black.

When read, this object returns last value written."
DEFVAL { white }
::= { labelEntry 5}

3.11.2.6 Label Start Row Parameter

labelStartRow OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-write
STATUS mandatory
DESCRIPTION "Start of text row number representing the vertical position on the screen where the text is to be displayed, with the display being scaled to a range of zero (0) to 255. Zero (0) is designated as the upper-most row ~~left corner~~ of the display. When read, this object returns last value written."
::= { labelEntry 6}

3.11.2.7 Label Start Column Parameter

labelStartColumn OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-write
STATUS mandatory

DESCRIPTION "Start of text column number representing the horizontal position on the screen where the text is to be displayed, with the display being scaled to a range of zero (0) to 255. Zero (0) is designated as the ~~upper~~ left-most column ~~corner~~ of the display. When read, this object returns last value written."
::= { labelEntry 7}

3.11.2.8 Label Status Parameter

labelStatus OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS ~~read-write~~ read-only
STATUS mandatory
DESCRIPTION "The object denotes whether or not the label is currently being displayed, as outlined below:

Bit7	0 = NO, 1 = YES denotes that the label is valid for display (MSB),
Bit6	0 = OFF, 1 = ON for the display status of the label,
Bits5..0	Reserved (Bit 0 = LSB)."

::= { labelEntry 8}

3.11.2.9 Label Active Control Parameter

labelActive OBJECT-TYPE
SYNTAX OCTET STRING (SIZE(1))
ACCESS read-write
STATUS mandatory
DESCRIPTION
"The object denotes whether or not the label is enabled for display.

Bit7	0 = DISABLED, 1 = ENABLED for display of the label (MSB),
Bits6..0	Reserved (Bit0 = LSB)."

::= { labelEntry 9}

3.11.2.10 Label Font Number Parameter

labelFontNumber OBJECT-TYPE
SYNTAX INTEGER (1..255)
ACCESS read-write
STATUS mandatory
DESCRIPTION
"Designates the font number to be displayed. Only one font style may be supported and that font style is taken to be the default style. When read, this object returns last value written.

Value	Meaning
1	other,
2	designates the default ASCII encoded text characters [0-9, A-Z , colon (:), period (.), slash (/), apostrophe (') and space ( )] to be displayed,
3..255	reserved."

DEFVAL { 2 }
::= { labelEntry 10}

3.11.3 Label Location Parameter

labelLocationLabel OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-write
STATUS mandatory
DESCRIPTION "Defines the label index ~~to~~ in the camera control label table for this camera location. The

location label is commonly used to identify a street name, intersection, or other pertinent information to be displayed on a monitor. A value of zero (0) turns the location reference label off at this location. When read, this object returns last value written."
::= {cctvLabel 3}

3.11.4 Enable Label Text Display

labelEnableTextDisplay OBJECT-TYPE
SYNTAX OCTET STRING (SIZE (1))
ACCESS read-write
STATUS mandatory
DESCRIPTION "The object provides a control mechanism for activating or deactivating all labels regardless of individual display status, as outlined below:

Bit7	0 = OFF, 1 = ON for the for controlling the display for all labels at once (MSB),
Bit6..0	Reserved (Bit 0 = LSB)."

::= {cctvLabel 4}

3.12 CCTV ON-SCREEN CAMERA MENU OBJECTS

cctvMenu OBJECT IDENTIFIER ::= { cctv 11 }

3.12.1 Activate Menu Parameter

menuActivate OBJECT-TYPE
SYNTAX INTEGER (0..255)
ACCESS read-write
STATUS mandatory
DESCRIPTION "Activates the internal camera menu.

Value	Meaning
0	turns off the internal camera menu,
1..254	activates the internal camera menu for the number of seconds expressed by the value indicated between 1 and 254,
255	activates the menu for an indefinite period of time."

::= {cctvMenu 1}

3.12.2 Menu Control Parameter

menuControl OBJECT-TYPE
SYNTAX INTEGER { pageDown(1),
pageUp(2),
cursorUp(3),
cursorDown(4),
cursorRight(5),
cursorLeft(6),
incrementValue(7) ,
decrementValue(8),
enterValue(9),
noMenu(255)}
ACCESS read-write
STATUS mandatory
DESCRIPTION "Object value that manipulates the internal camera menu. Basic menu manipulations are described as follows:

Value	Meaning
1	Page Down,

```
        2               Page Up,
        3               Cursor Up
        4               Cursor Down,
        5               Cursor Right,
        6               Cursor Left,
        7               Increment value pointed at current cursor position,
        8               Decrement value pointed at current cursor position,
        9               Enter value shown,
        10..254         Reserved,
        255             Menu not supported by the device."
::= {cctvMenu 2}


END
```

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Section 4
CONFORMANCE

4.1 CONFORMANCE GROUPS

A conformance group is defined in NTCIP 1101 Simple Transportation Management Framework (STMF), clause 3.3.5, as a basic unit of conformance.

Conformance groups are defined as either mandatory or optional. If a conformance group is mandatory, all of the objects and subgroups with STATUS "mandatory" that are part of the conformance group shall be present for a device to claim conformance to the MIB defining the Conformance group. If a Conformance group is optional, all of the objects and subgroups with the STATUS "mandatory" that are part of the conformance group shall be present if the device supports the Conformance group. Optional objects with the STATUS "optional" may be supported.

When a table is included in a conformance group, all objects contained in the table are included by reference. This is because a table is defined as a SEQUENCE OF {SEQUENCE}. Thus, all objects listed in the sequence are defined as an integral part of the table. Tables are defined as either mandatory or optional. If a table is mandatory, all of the objects with STATUS "mandatory" shall be present. If a table is optional, all of the objects with the STATUS "mandatory" shall be present if the device supports the table. Optional objects within a table with the STATUS "optional" may be supported.

Support for objects within a Subgroup are handled in the same fashion as tables. This is summarized in Table 4-1.

TABLE 4-1: OBJECT SUPPORT REQUIREMENTS

OBJECT STATUS	TABLE STATUS	CONFORMANCE GROUP STATUS (IF ANY)	OBJECT SUPPORT
mandatory	Mandatory	mandatory	mandatory
mandatory	Mandatory	optional	mandatory, if conformance group is supported
mandatory	Optional	mandatory	mandatory, if table is supported
mandatory	Optional	optional	mandatory, if both the conformance group and table are supported
optional	Mandatory	mandatory	optional
optional	Mandatory	optional	optional
optional	Optional	mandatory	optional
optional	Optional	optional	optional

The Conformance Group definitions for Closed Circuit Television (CCTV) are defined in the following Clauses. A CCTV may have multiple capabilities; thus, Conformance Groups are defined for each capability.

4.1.1 CCTV Configuration Conformance Group

The Configuration Conformance Group consists of objects that specify the configuration parameters of a CCTV. The conformance requirement for each object within the group is shown. Please refer to the Conformance Statement Table 4-2 for the conformance requirement for the group. The Configuration Conformance Group shall consist of the following objects:

OBJECT OR TABLE NAME	REFERENCE	CONFORMANCE REQUIREMENT WITHIN THE GROUP
rangeMaximumPreset	NTCIP 1205, Amend 1	mandatory
rangePanLeftLimit	NTCIP 1205, Amend 1	mandatory
rangePanRightLimit	NTCIP 1205, Amend 1	mandatory
rangePanHomePosition	NTCIP 1205, Amend 1	mandatory
rangetTrueNorthOffset	NTCIP 1205, Amend 1	mandatory
rangeTiltUpLimit	NTCIP 1205, Amend 1	mandatory
rangeTiltDownLimit	NTCIP 1205, Amend 1	mandatory
rangeZoomLimit	NTCIP 1205, Amend 1	mandatory
rangeFocusLimit	NTCIP 1205, Amend 1	mandatory
rangeIrisLimit	NTCIP 1205, Amend 1	mandatory
rangeMinimumPanStepAngle	NTCIP 1205, Amend 1	mandatory
rangeMinimumTiltStepAngle	NTCIP 1205, Amend 1	mandatory
timeoutPan	NTCIP 1205, Amend 1	mandatory
timeoutTilt	NTCIP 1205, Amend 1	mandatory
timeoutZoom	NTCIP 1205, Amend 1	mandatory
timeoutFocus	NTCIP 1205, Amend 1	mandatory
timeoutIris	NTCIP 1205, Amend 1	mandatory
labelMaximum	NTCIP 1205, Amend 1	mandatory
labelTable	NTCIP 1205, Amend 1	mandatory
labelEntry	NTCIP 1205, Amend 1	mandatory
labelIndex	NTCIP 1205, Amend 1	mandatory
labelText	NTCIP 1205, Amend 1	mandatory
labelFontType	NTCIP 1205, Amend 1	~~mandatory~~ deprecated
labelHeight	NTCIP 1205, Amend 1	mandatory
labelColor	NTCIP 1205, Amend 1	mandatory
labelStartRow	NTCIP 1205, Amend 1	mandatory
labelStartColumn	NTCIP 1205, Amend 1	mandatory
labelStatus	NTCIP 1205, Amend 1	mandatory
labelActive	NTCIP 1205, Amend 1	mandatory
labelFontNumber	NTCIP 1205, Amend 1	mandatory
labelLocationLabel	NTCIP 1205, Amend 1	mandatory
labelEnableTextDisplay	NTCIP 1205, Amend 1	mandatory

4.1.2 Extended Functions Conformance Group

The Features Conformance Group consists of objects that specify features within a CCTV. The conformance requirement for each object within the group is shown. Please refer to the Conformance Statement Table 4-2 for the conformance requirement for the group. The Features Conformance Group shall consist of the following objects:

OBJECT OR TABLE NAME	REFERENCE	CONFORMANCE REQUIREMENT WITHIN THE GROUP
systemCameraFeatureControl	NTCIP 1205, Amend 1	mandatory
systemCameraFeatureStatus	NTCIP 1205, Amend 1	mandatory
systemCameraEquipped	NTCIP 1205, Amend 1	mandatory
systemLensFeatureControl	NTCIP 1205, Amend 1	mandatory
systemLensFeatureStatus	NTCIP 1205, Amend 1	mandatory
systemLensEquipped	NTCIP 1205, Amend 1	mandatory
alarmStatus	NTCIP 1205, Amend 1	mandatory
alarmLatchStatus	NTCIP 1205, Amend 1	mandatory
alarmLatchClear	NTCIP 1205, Amend 1	mandatory
alarmTemperatureHighLowThreshold	NTCIP 1205, Amend 1	mandatory
alarmTemperatureCurrentValue	NTCIP 1205, Amend 1	mandatory
alarmPressureHighLowThreshold	NTCIP 1205, Amend 1	mandatory
alarmPressureCurrentValue	NTCIP 1205, Amend 1	mandatory
alarmWasherFluidHighLowThreshold	NTCIP 1205, Amend 1	mandatory
alarmWasherFluidCurrentValue	NTCIP 1205, Amend 1	mandatory
alarmLabelIndex	NTCIP 1205, Amend 1	mandatory
alarmLabelSource	NTCIP 1205, Amend 1	mandatory
inputStatus	NTCIP 1205, Amend 1	mandatory
inputLatchStatus	NTCIP 1205, Amend 1	mandatory
inputLatchClear	NTCIP 1205, Amend 1	mandatory
inputLabelIndex	NTCIP 1205, Amend 1	mandatory
inputPresetIndex	NTCIP 1205, Amend 1	mandatory
inputLabelSource	NTCIP 1205, Amend 1	mandatory
outputStatus	NTCIP 1205, Amend 1	mandatory
outputControl	NTCIP 1205, Amend 1	mandatory
outputLabelIndex	NTCIP 1205, Amend 1	mandatory
zoneMaximum	NTCIP 1205, Amend 1	mandatory
zoneTable	NTCIP 1205, Amend 1	mandatory
zoneEntry	NTCIP 1205, Amend 1	mandatory
zoneIndex	NTCIP 1205, Amend 1	mandatory
zoneLabel	NTCIP 1205, Amend 1	mandatory
zonePanLeftLimit	NTCIP 1205, Amend 1	mandatory
zonePanRightLimit	NTCIP 1205, Amend 1	mandatory
zoneTiltUpLimit	NTCIP 1205, Amend 1	mandatory
zoneTiltDownLimit	NTCIP 1205, Amend 1	mandatory
zoneVideoControl	NTCIP 1205, Amend 1	mandatory
zoneCameraEquipped	NTCIP 1205, Amend 1	mandatory

4.1.3 Motion Control Conformance Group

The Motion Control Conformance Group consists of objects that specify features within a CCTV. The conformance requirement for each object within the group is shown. Please refer to the Conformance Statement Table 4-2 for the conformance requirement for the group. The Motion Control Conformance Group shall consist of the following objects:

OBJECT OR TABLE NAME	REFERENCE	CONFORMANCE REQUIREMENT WITHIN THE GROUP
presetGotoPosition	NTCIP 1205, Amend 1	mandatory
presetStorePosition	NTCIP 1205, Amend 1	mandatory
presetPositionQuery	NTCIP 1205, Amend 1	mandatory
positionPan	NTCIP 1205, Amend 1	mandatory
positionTilt	NTCIP 1205, Amend 1	mandatory
positionZoomLens	NTCIP 1205, Amend 1	mandatory
positionFocusLens	NTCIP 1205, Amend 1	mandatory
positionIrisLens	NTCIP 1205, Amend 1	mandatory
positionQueryPan	NTCIP 1205, Amend 1	mandatory
positionQueryTilt	NTCIP 1205, Amend 1	mandatory
positionQueryZoom	NTCIP 1205, Amend 1	mandatory
positionQueryFocus	NTCIP 1205, Amend 1	optional
positionQueryIris	NTCIP 1205, Amend 1	optional

4.1.4 On-Screen Menu Control Conformance Group

The On-Screen Menu Control Group consists of a variety of CCTV objects related to general configuration information. The conformance requirement for each object within the group is shown. Please refer to the Conformance Statement Table 4-2 for the conformance requirement for the group. The On-Screen Menu Control Conformance Group shall consist of the following objects and tables:

OBJECT OR TABLE NAME	REFERENCE	CONFORMANCE REQUIREMENT WITHIN THE GROUP
menuActivate	NTCIP 1205, Amend 1	mandatory
menuControl	NTCIP 1205, Amend 1	mandatory

4.2 CONFORMANCE STATEMENTS

CCTV Cameral Control devices shall adhere to the conformance requirements specified in TABLE 4-2 as a minimum to claim compliance to this standard. Additional objects or groups may be supported without being non-compliant with CCTV Camera Control objects or NTCIP.

Minimum and maximum ranges of objects that differ from the values of the object's SYNTAX field may be enforced by an application running on a device.

A device that enforces range limits within the bounds specified by the values of the object's SYNTAX field shall not be categorized as being non-compliant with CCTV Camera Control objects or NTCIP.

A device that supports a subset of enumerated values for a given object shall not be categorized as being non-compliant with CCTV Camera Control objects or NTCIP.

TABLE 4-2: CONFORMANCE STATEMENT TABLE

CONFORMANCE GROUP	REFERENCE	CONFORMANCE REQUIREMENT
Configuration	NTCIP 1201, Amendment 1	mandatory
~~Database Management~~	~~NTCIP 1201, Amendment 1~~	~~optional~~
~~Time Management~~	~~NTCIP 1201, Amendment 1~~	~~optional~~
Security	NTCIP 1201, Amendment 1	mandatory
CCTV Configuration	NTCIP 1205, Amendment 1	mandatory
Extended Functions	NTCIP 1205, Amendment 1	optional
Motion Control	NTCIP 1205, Amendment 1	optional
On-Screen Menu Control	NTCIP 1205, Amendment 1	optional

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Annex A
EXTENDED GLOSSARY

(Informative)

Aberrations	Certain aberrations degrade the image formed by a lens.
A/B Editing	Video editing using two source recorders.
A/B Roll Editing	A technique by which selected odd (A-roll) and even (B-roll) audio/video sequences from two VCRs are then dubbed onto a third tape usually a composite master.
A/B Split Screen	A useful means for comparing two sources simultaneously. Permits a fast visual check of the phase and sync timing between two inputs.
Ablation	Optical memory data writing technique in which laser burns pits onto a metal film.
Achromatic	Completely colorless white light.
Active Line	The horizontal scan lines which produce a television picture. In the NTSC system in the US, there are 525 active lines.
Active Program	The length of audio and video program material on the master videotape not to exceed the one-side capacity of a videodisc.
Active Video Lines	All video not occurring in the horizontal and vertical blanking intervals.
ACTV1	A channel/receiver compatible system with increased resolution.
ACTV2	Similar to ACTV1 but with improved audio and still more advanced resolution.
Advanced Compatible Television (ACTV)	Advanced television transmission system; currently two such systems exist.
Advanced Interactive Video (AIV)	A format for storing analog and digital video images, digital sound and data on a single laser disc.
Advanced Television (ATV)	Including several versions of improved or higher quality television, including HDTV, IDTV, EDTV, and several other television systems considered better than the currently available and used systems.
Aliasing	Undersirable "beating" effects caused by sampling frequencies being too low to faithfully reproduce image detail.
Alpha Channel	A portion of each display pixel representing the combined video and graphic image data for a video digitizer component.
Alphageometric	A videotex graphics format in which shapes are defined by geometric elements such as points and lines.
Alphamosaic Graphics	A videotex graphics format in which pictures are composed of small character sized blocks.
Analog Video	A video signal that represents an infinite number of gradations between given video levels.

Anamorphic	A type of lens adapter designed to produce a wide screen image from an equally condensed image on the film.
Aperture	The opening of a lens which controls the amount of light reaching the surface of the pickup device. The size of the aperture is controlled by the iris adjustment. By increasing the f stop number (f/1.4, f/1.8, f/2.8, etc.) less light is permitted to pass to the pickup device.
Aspect Ratio	The proportions of a projected picture area in terms of relative height and width values. In the U.S., standard video aspect ratio is four units wide by three units high, usually shown as 4:3.
Astigmatism	The uneven foreground and background blur that is in the image.
Asymmetrical Compression	An image compression system which takes more processing to compress the image than it does to extract or decompress it.
Auto Brightness Control	The electronic circuit which controls the brightness of the display device as a function of ambient light.
Automatic Frequency Control (AFC)	An electronic circuit used whereby the frequency of an oscillator is automatically maintained within specified limits.
Automatic Gain Control (AGC)	An electronic circuit used by which the gain of a signal is automatically adjusted as a function of its input or other specified parameter.
Automatic Light Control (ALC)	The process by which the illumination incident upon the face of the pickup device is automatically adjusted as a function of the brightness of the scene.
Automatic Pan (Scan)	Continuous, automatic horizontal back and forth motion of a camera.
Automatic Sensitivity Control (ASC)	(A) Electronic circuit which varies the sensitivity of the system as a function of automatic target control, automatic light controls, other specified control parameters, or any combination thereof. (B) Detects light intensity and keeps camera in optimum working condition as it applies to light input.
Automatic Iris Lens	A lens in which the aperture automatically opens or closes to maintain proper light levels on the faceplate of the camera pickup device.
Automatic Light Control (ALC)	A circuit used in audio and video recorders to control the level of the recorded signal automatically to provide uniform level without distortion due to overloading. Also called Automatic Gain Control (AGC). An ALC Defeat control permits manual level control for wide ranges or special recording purposes.
Back Light	A fixture that is often not properly applied or overlooked completely. The main function of the back light is to separate the individual subjects from the background and give them depth and dimension.
Barrel Distortion	The distortion of a scene which occurs when a wide-angle lens is used; edges appear rounded and out of proportion with the center of the image.
Base and Fill Lights	Commonly referred to as "scoops" provide a soft-edged field of light which is used to provide basic illumination of the subject. to fill in the areas not highlighted by the key light, to illuminate the background and to soften shadowed caused by key lights.
Blackburst	A composite color video signal. This signal has composite sync,

	reference burst, and a black video signal which is usually at a level of 7.5 IRE 1 .05V) above the blanking level. (B) Fade-to-Black between scenes.
Black Level	The level of the video signal that corresponds to the maximum limits of the black areas of the picture.
Blanking	Related to composite sync. This signal has both horizontal and vertical components and is at its negative level whenever video is to be blanked or turned off.
Blanking Level	It is the level of a video signal which separates the range that contains the picture information from the range that contains the synchronizing information.
Bloom	Unacceptable TV picture caused by too much light.
Brightness	Achromatic intensity, relative lighting without regard to color; light emitted from a surface such as a screen measured in foot-lamberts, foot-candles, or lux.
Brightness Ratio	The difference between the brightest and darkest object in a scene. Too extreme a difference can lead to an unacceptable contrast ratio.
Brightness Signal	Same as the luminance signal (Y); the signal which carries information about the amount of light at each point in the image.
Burst	In color TV reception, the signal that serves as the reference for the 3.58 MHz oscillator; it occurs during video blanking.
Character Generator	Reproduces recognized font styles from a computer type keyboard-usually provides multiple screen storage and is capable of background colorization from video display.
Charge-Coupled Device (CCD)	Semiconductor devices arrayed so that the electric charge at the output of one provides the input stimulus to the next. More compact and efficient than cathode ray tubes.
Chroma	The color information contained in a video signal, consisting of hue (phase angle) and saturation (amplitude) of the color subcarrier.
Chroma Keying	The process of overlaying one video signal over another, the areas of overlay being defined by a specific range of color, or chrominance, one of the signals. For this process to work, the chrominance must have sufficient resolution, or bandwidth. Coded (composite) video systems do not have sufficient bandwidth for acceptable quality chroma keying, hence analog chroma keyers typically use RGB sources.
Chrominance	The color part of a signal, relating to the hue and saturation but not to the brightness or luminance of the signal, e.g. black, gray and white, have no chrominance, but any colored signal has both chrominance and luminance. U,V: Cr,Cb: 1,Q:(R-Y), (B-Y) represent the chrominance information of a signal.
Clipping	The process of shearing off the peaks of either the white or the black excursions of the video signal.
Closed Circuit Television (CCTV)	A distribution system which limits reception of an image to those receivers or monitors which are directly connected to the origination point by coaxial cable or microwave link.
Closed Loop	A continuous loop of film or tape for repetitive playing, often in a

	cartridge.
Coder-Decoder (CODEC)	A device for encoding a signal for transmission and decoding it upon receipt of transmitted signals.
Color Lookup Table (CLUT)	A selection of colors assigned a digital value and held in a table. A program then decodes a color image for display by matching the code stored for each pixel with the associated color value in the look-up table.
Color Bars	SMPTE standard test bars used to match playback with original recording levels. Often accompanied by a 1000 Hz audio tone.
Color Burst	A few (8 to 10) cycles of 3.58MHz color subcarrier which occur during the back porch interval. Color burst amplitude is 40 IEEE units and phase is 1800. The color oscillator of a color television receiver is phase locked to the color burst.
Color Correction	A process in which the coloring in a television image is altered or corrected by electronic means. Care must be taken to insure that the modified video does not exceed the limits of subsequent processing or transmission systems.
Color Cycling Animation	The color of individual pixels are changed to give the effect of movement.
Colorization	Adding color to an originally black-and-white image.
Color Map	A table which stores the values of the red, green, and blue (RGB) components of colors in a computer graphics system to be displayed on the monitor.
Color Phase	The correct timing relationship within a color display-color is considered to be in-phase when the hue is reproduced correctly.
Colorplexer	An encoder which combines the separate red, green, and blue signals into one composite video signal.
Color Subcarrier	The 3.58MHz signal which carries color information. This signal is superimposed on the luminance level. Amplitude of the color sub-carrier represents saturation and phase angle represents hue.
Color Temperature	The color tint expressed in degrees Kelvin (K) of the light source. The higher the color temperature, the bluer the light; the lower the temperature, the redder the light.
Community Antenna Television (CATV)	Usually referred to as cable television.
Compact Disc (CD)	A 4.75" (12 cm) laser-encoded optical disc that contains information encoded digitally in the constant linear velocity (CLV) spiral format.
Compact Disc+Graphics (CD+G)	A CD format which includes extended graphics capabilities.
Compact Disc-Interactive (CD-I)	A CD format which provides audio, digital data, still graphics, and limited motion video. The standard for this format is known as the Green Book.
Compact Disc-Interactive Video	A CD format which provides audio, digital data, still graphics, and full-screen, full-motion video.

(CD-IV)	
Compact Disc-Music Instrument Digital Interface (CD+MIDI)	A CD format which provides digital audio, graphics information, and the musical instrument digital interface (MIDI) specifications and capabilities.
Compact Disc-Read Only Memory	A 4.75" (12 cm) laser-encoded optical memory storage medium that contains information encoded digitally in the constant linear velocity (CLV) spiral format. The standards for this format are known as the Yellow Book.
Component Analog Video (CAV)	Unencoded video signals which can provide greater color resolution. An NTSC encoder must be used to read the signals so they may be recognized by a standard NTSC receiver.
Compatible Color	A video broadcast system which separates the luminance and chrominance signals so that the signal may be received by either a color or black and white receiver.
Component	The normal interpretation of a component video signal is one in which the luminance and chrominance are sent as separate components.
Component Video	The separation of chrominance and luminance parts of the video signal. These two component signals are recorded separately.
Composite	A composite video signal is one in which the luminance and chrominance information have been combined using one of the coding standards: NTSC, PAL, SECAM.
Composite Sync	A signal consisting of horizontal sync pulses, vertical syncpulses, and equalizing pulses only, with a no-signal reference level.
Composite Video Signals	The complete visual wave form of the color video signal composed of chromatic and luminance picture information; blanking pedestal; field, line, and color sync pulses; and field equalizing pulses.
Compressed Video	A video image or segment that has been digitally processed using a variety of algorithms and other techniques to reduce the amount of space required to store the digital information.
Contrast	(A) The range of light and dark values in a picture or the ratio between the maximum and the minimum brightness values. Low contrast is shown mainly as shades of gray, while high contrast is shown as blacks and whites with very little gray. (B) A TV monitor adjustment which increases or decreases the level of contrast of a televised picture.
Contrast Range	The range of grays in a video image, usually a ratio of light to dark.
Contrast Ratio	The ratio of brightness of the brightest possible area to the darkest possible area of an image.
Convergence	Proper alignment of the vertical and horizontal lines, as in video projection.
Cross Color	This defect manifests itself as spurious rainbow patterns on highly textured objects like the one found on a striped shirt or tweed jacket. Cross-color defect is attributed to the make-up of the NTSC signal which mixes the high luminance and chrominance information in the same composite baseband spectrum.
Cross Luminance	More generally referred to as "Dot Crawl", this defect appears as a dot

	pattern crawling up or hanging on the edges of color areas. This is also a result of the NTSC signal structure where the color information leaks into the luminance signal.
Definition	The sharpness/resolution of a picture.
Depth of Field	The front to back zone in a field of view which is in focus in the televised scene. With a greater depth of field, more of the scene, near to far, is in focus.
Encoded	The encoded video signal is formed by starting with an RGB signal from the color television camera. This RGB signal is then processed through an I and 0 encoder which converts the RGB into a composite NTSC signal. The encoded signal has all of the elements of the composite video signal: sync, burst, chroma, and luminance.
Encoder Video	Devices that change individual component signals into composite signals. For example, an encoder combines Y (luminance or light) and C (chrominance or color) signals to provide a video image.
Enhanced Definition Television also Extended Definition Television (EDTV)	An advanced television system with advanced encoding and transmission methods but not as sophisticated as HDTV.
Equalizer	(A) Equipment designed to compensate for loss and delay frequency effects within a system. (B) A component, or circuit, which allows for the adjustment of a signal across a given band.
f /number	In lenses with adjustable irises, the maximum iris opening is expressed as a ratio, (focal length of the lens)/(maximum diameter of aperture). This maximum iris will be engraved on the front ring of the lens.
Field	One-half of a television picture. One complete vertical scan of the picture, containing 262.5 lines. Two fields make up a complete television picture (frame). The lines of Field 1 are vertically interlaced with Field 2 for 525 lines of resolution.
Field Frequency	The number of fields per second is the field frequency; NTSC field frequency is 60 per second; PAL and SECAM frequencies are 50.
Flicker	A video effect on a still or frozen frame caused when the two fields that make one video picture frame are not identically matched, thus creating two different pictures alternating every 1/60 of a second.
Flutter	Rapid change in frequency of an audio or video signal due to variations in tape or disk speed. Wow is usually considered a lower frequency speed variation.
Focal Length	The distance from the center of the lens to a plane at which point a sharp image of an object viewed at an infinite distance from the camera is produced. The focal length determines the size of the image and the angle of the field of view seen by the camera through the lens. That is the distance from the center of the lens to the pickup device.
Focus	Sharpening a blurred image on a screen, monitor, or any display; adjusting picture to achieve the greatest possible resolution.
Focus, Automatic	A device on slide projectors whereby after focusing the first image, remaining similarly-mounted slides are automatically focused.
Foot Candle	The amount of light reflected by a surface one foot from a lighted

	candle. Metric equivalent is lux.
Foot Lambert	One lumen or one foot candle of light over a one square foot surface.
Format, Video	Current formats include C, U-Matic, Betacam, M, Betacam SP, M-11, DI, D2, Beta, VHS, Hi8, 8mm and S-VHS.
Frame	(A) The total area of the picture which is scanned while the picture signal is not blanked. (B) A complete TV picture consisting of two fields; a total scanning of all 525 lines of the raster area; occurs every 1/30 of a second. (625 lines, 1/25 sec. in Europe and many other countries).
Frame Rate	The speed at which video frames are scanned or displayed; 30 frames a second for NTSC; 25 frames a second for PAL/SECAM.
Genlock	Genlock is a process of sync generator locking. This is usually performed by introducing a composite video signal from a master source to the subject sync generator. The generator to be locked has circuits to isolate vertical drive, horizontal drive and subcarrier. The process then involves locking the subject sync generator to the master subcarrier, horizontal, and vertical drives so that the result is that both sync generators are running at the same frequency and phase.
Ghost	A shadowy or weak image in the received picture, offset either to the right or to the left of the primary image. It is the result of transmission conditions where secondary signals are created and received earlier or later than the primary signal caused by a reflected RF signal.
Gray Scale	A series of tones which range from true black to true white, it is usually expressed in 10 steps.
High-Definition Television (HDTV)	A variety of video formats offering greater visual accuracy (or resolution) than current NTSC, PAL, or SECAM broadcast standards. Current formats generally range in resolution from 655 scanning lines to 2,125 scanning lines, having an aspect ratio of 5:3(or 1.67:1), and a video bandwidth of 30 MHz to 50 MHz which is 5+ times greater than NTSC standard. Digital HDTV has a bandwidth of 300+ MHz.
High Resolution	Camera or monitor with a great number of scanning lines (1000-2000) which produces a very sharp, detailed image.
Horizontal Blanking Interval	The time required for the picture-forming beam of a CRT to return from the start of one line to the start of the next line.
Horizontal Blanking Signal	The blanking signal that is produced at the end of each scanning line.
Horizontal Drive	This signal is derived by dividing sub-carrier by 227.5 and then doing some pulse shaping.
Horizontal Resolution	Smallest increment of a television picture that can be discerned in the horizontal plane.
Horizontal Sync	This signal is derived by dividing sub-carrier by 227.5 and then doing some pulse shaping. The signal is used by monitors and cameras to determine the start of each horizontal line.
Hue	A) Distinction between colors. Red, blue, green, yellow, etc. are hues. White, black, and gray are not considered hues. (B) The dimension of color that is referred to a scale of perceptions ranging from red through yellow, green, blue back to red.
Interlace	The pattern described by the two separate field scans when they join

	to form a complete video frame.
Interlaced	The process of scanning whereby the alternate lines of both scanned fields fall evenly between each other.
Interlacing	Increasing video resolution by doubling the number of horizontal scan lines. NTSC video is interlaced.
Interleaving	A method of storing information sequences in an alternating series of frames and playing the sequences using a computers capabilities to achieve continuous play of a segment.
Intraframe Coding	A method to compress a video signal for transmission in which half the picture information is eliminated by dropping every other frame as it comes from the camera. At playback, each frame remains on the screen twice the normal duration to simulate the standard 30 frame/second video rate.
Interfield Flicker	A video effect that occurs when field dominance is incorrectly specified or if field dominance changes at one or more points on the master tape from having been edited on equipment that is incapable of frame-accurate editing.
Iris	The amount of light transmitted through a lens is controlled by an adjustable diaphragm, or iris, located in the lens barrel. The opening is referred to as the aperture, and the size of the aperture is controlled by rotating the aperture control ring on the lens barrel. The graduations on the lens barrel are expressed in terms of the focal length for the lens divided by the diameter of the aperture at that setting. This ratio is called the f-number.
Lens Speed	Refers to the ability of a lens to pass light expressed as a ratio: the focal length of the lens divided by the (effective) diameter. A fast lens which passes more light might be rated f / 1.1 or 1.2; a much slower lens which passes less light might be designated f / 3.5 The f / number = focal length / aperture.
Line-Lock	Synchronizes camera to power line zero crossing for roll-free vertical interval switching. Vertical phase delay can be externally adjusted (continuously) to allow vertical synchronization in multiphase power installations.
Looping	A term indicating that a high impedance device has been permanently connected in parallel to a video source.
Lumen	A measurement of quantity of light taken at the source of the light. Lumens per square foot are foot candles.
Luminance	Brightness; one of the three image characteristics coded in composite television represented by the letter Y.
Lux	The metric measurement of light quantity. The measurement is taken from the reflection off the object illuminated. One foot-candle equals 10.76 lux. A lux equals one lumen per square meter.
Macro	A series of commands batched together and executable through one or a few keystrokes.
M, M Format	Portable camera/recorder system developed by Panasonic; also used for just the recorder or the interconnect format. "M" actually refers to the manner in which the video tape is wrapped around the head drum. M format systems employ the (V, I, 0) component set.

MII (M2). MII Format	Second generation camera/recorder system developed by Panasonic; also used for just the recorder or the interconnect format. MII uses a version of the (V, R-Y, B-Y) component set.
Moiré	(A) A wavy or satiny effect produced by the convergence of lines. It usually appears as a curving of the lines in the horizontal wedges of a test pattern. It is a natural optical effect when converging lines in a television picture are nearly parallel to the scanning lines. (B) Optical disturbance caused by interference of similar frequencies.
Multi-standard Decoder	A device that converts NTSC, PAL, SECAM or NTSC 4.43 video to RGB video.
National Television System Committee (NTSC)	The organization which formulated the "NTSC" system; Usually taken to mean the NTSC color television system itself, or its interconnect standards. The US standard 525 line 60 field system.
Neutral Colors	The range of gray levels, from black to white, but without color. For neutral areas in the image the RGB signals will all be equal, in color difference formats the color difference signals will be zero.
Non-Interlace	A scanning system that repeats the exact vertical retrace period for every field, resulting in every other scan line in a 525 line system being refreshed 60 times a second. This results in a flicker-free image with half the vertical resolution.
Non-Interlaced	A video scanning system where the horizontal lines are scanned from top to bottom in order, as opposed to interlaced, where the lines are scanned in two passes, odd lines on one pass and even lines on another.
NTSC Color Bars	A pattern generated by the NTSC Generator, consisting of eight equal width color bars. Colors are white (75%), black (7.5% set-up level), 75% saturated pure colors red, green, and blue, and 75% saturated hues of yellow, cyan, and magenta. Mixtures of two colors in 1:1 ratio without third color.
NTSC Format	A color television format having 525 scan lines; a field frequency of 60 Hz.; a broadcast bandwidth of 4 MHz., line frequency of 15.75 kHz.; frame frequency of 1/30 of a second; and a color subcarrier frequency of 3.58 MHz.
NTSC Video 4.43	This term refers to the video output of video tape or disk players used mainly in Middle East countries.
Overscan	Deliberate scanning in a television set or monitor in which the active display area of the CRT is filled with slightly less than the complete video image. This enables the physical edges of the display device to become the picture's borders rather than the blanking portions of the signal.
PAL-M	Phase Alternation by Line, Brazilian broadcast standard which consists of 525 lines and 60 fields per second.
Pan	Movement of the camera in a horizontal direction.
Persistence	The rate of decay of the visible glow from a CRT's phosphor, when the scanning electron beam is no longer applied. Monitors with a long persistence phosphor will have less visible flicker, but may show smearing when images are moved on the screen.
Phase Alternate by	, 625 line 50 field composite color transmission system, used in Great

Line (PAL)	Britain, Ireland, Western Europe, Scandinavia, South Africa and Australia. The phase alternation makes the signal relatively immune to certain distortions compared to NTSC.
Raster	The rectangular pattern of scanning lines upon which the picture is produced. The illuminated face of the TV monitor without the video information present.
Resolution	(A) A measure of the ability of a camera or television system to reproduce detail. That is the number of picture elements that can be reproduced with good definition, It is a factor of the pickup device or the TV CRT characteristics and the video signal bandwidth. (B) Generally called horizontal resolution. It can be evaluated by establishing the limit to which lines can be distinguished on a test pattern. A larger resolution value means a broader frequency band of the video signal. (C) A measure of the greatest amount of detail that can be seen, or resolved, in an image.
Retrace	The blank portion of the video signal, while the electron beam moves without producing an image.
Red, Green, Blue (RGB)	The chrominance information in a video signal.
RGB, RGB Format, RGB System	Red, Green, and Blue: The basic parallel component set, in which a signal is used for each primary color; or the related equipment or interconnect formats or standards.
RGB Sync	Red, green, blue and sync, same as RGB but with additional sync channel.
RGB Video	Computer video output which can be analog or digital. Analog RGB video has 3,4, or 5 wires; one for the red, one for the green, one for the blue video and one or two for the sync.
Saturation	Quantity of pure color, which is diluted when mixed with white.
SEquential Couleur A Memoire (SECAM)	or sequential color and memory. A color W system with 625 lines and 50 fields developed in France different from NTSC and PAL systems. Used in France, Russia and Eastern Europe.
Sequential Switcher	A video control device that switches multiple video inputs to multiple video outputs in a predetermined timed sequence.
Switcher	Term often used to describe a special effects generator; a unit which allows the operator to switch between video camera signals. Switchers are often used in industrial applications to switch between video cameras monitoring certain areas for display on one monitor.
Sync	This signal is derived from a composite or combination of horizontal and vertical drives, with some slightly narrowed and delayed pulses as well as the addition of equalizing pulses.
Sync generator	A device which generates a signal which can be read by several types of equipment. The signal is used to keep all equipment running together.
Tilt	The movement of a camera in a vertical direction.
Underscan	Decreases raster size H and V so that all four edges of the picture are visible on the monitor. Allows viewing of skew and tracking which would not be visible in normal (overscanned) mode. Also helpful when aligning test charts to be certain they touch all four corners of the

	raster. Likewise, when checking the alignment of multiplexer images from a film chain, underscan allows proper framing of the projected image going into the video camera.
Vertical Interval Time Code (VITC)	(Vertical Interval Time Code): This is the same information as the SMPTE time code. It is superimposed onto the vertical blanking interval, so that the correct time code can be read even when a helical scanning VCR is in the Pause or Slow mode.
Vertical Retrace	The return of the electron beam to the top of a television picture tube screen or a camera pickup device target at the completion of the field scan.
Vertical Sync Pulse	A portion of the vertical blanking interval which is made up of blanking level and six pulses (92% duty cycle at -40 IEEE units) at twice the horizontal sync pulse repetition rate. Synchronizes vertical scan of television receiver to composite video signal. Starts each frame at same vertical position (sequential fields are offset 1/2 line to achieve interlaced scan).
Video	Pertaining to picture signals in a television system. (A): any production using videotape or television technology. (B): Television and the technical equipment and events involved in creating television. (C): The picture portion of a television broadcast. (D): Non-broadcast or private television.
Video Distribution Amplifier	A special amplifier for strengthening the video signal so that it can be supplied to a number of video monitors at the same time.
Video Tape Recorder (VTR)	The term "VTR" includes reel-to-reel and cassette type.
VTR	Video Tape Recorder, the term "VTR" includes reel-to-reel and cassette type.
White Balance	(A) White balance is considered the reference color with which all other colors in an image are compared against. Auto white balance detects white colors in an image as a reference for other colors in the field of view. (B) A method of resetting the balance on a video camera by shooting a white card which adjusts the camera to the color temperature of the card.
White Level Set	White set; a camera control which establishes the luminance level for a color camera.
Y Signal	The luminance signal transmitted in standard color video.
Y/C	A set of video signals that contain a separate Y, which is luminance, and C, which is chroma. Usually the chroma is at 3.58MHz, as in the S-Video signal. but it can also be at 688kHz in the 3/4" dub format.
Y, Cl, C2	A generalized set of CAV signals: Y is the luminance signal. C1 is the 1st color difference signal and C2 is the 2nd color difference signal.
Y, I, Q	The set of CAV signals specified for the NTSC system: Y is the luminance signal. I is the 1St color difference signal and 0 is the 2nd color difference signal.
Y, Pb, P,	A version of Y, R-Y, B-Y specified for the SMPTE analog component standard.
Y, R-Y, B-Y	The general set of CAV signals used in the PAL system as well as for some encoder and most decoder applications in NTSC systems; Y is

	the luminance signal. R-Y is the 1st color difference signal and B-Y is the 2nd color difference signal.
Y, U, V,	Luminance and color difference components for PAL systems; Y, BV, R-Y with new names; the derivation from RGB is identical.
Zoom	A zoom lens is unique because its focal length can be changed while the object being viewed remains in focus.
Zoom Ratio	A mathematical expression of the two extremes of focal length available on a particular zoom lens.

Annex B
INFORMATION PROFILE

(Informative)

A Conformance Group is a basic unit of conformance and is used to specify a collection of related managed objects. The Conformance Group designation applied to a set of objects provides a systematic means for determining which objects are required to support a function. If a device has multiple functions, a Conformance Group will be defined for each function. Conformance Group definitions will be found in the NTCIP Object Definition Standard documents. The Object Definition Standard may define a Conformance Group with objects that are not in lexicographic order and only apply to devices of that type.

The related managed objects of a Conformance Group may include mandatory and/or optional objects. Mandatory objects within a Conformance Group shall be implemented. Optional objects shall be implemented only if a defined function of the device requires that particular object.

For example, assume a device implements an asynchronous RS-232 interface. It must implement all the mandatory objects in the Asynchronous Conformance Group of the RS-232 MIB. It would not have to implement the Synchronous Conformance Group of objects unless it also provided a synchronous interface.

Assume also that the Asynchronous Conformance Group has a *CRC error counter* object that is optional. The *CRC error counter* object would not have to be implemented unless the device used CRC checking on the asynchronous interface.

Conformance Groups are defined as either mandatory or optional. If a Conformance Group is mandatory, all of the objects with STATUS "mandatory" that are part of the Conformance Group shall be present for a device to claim conformance to the Conformance Group. If a Conformance Group is optional, all of the objects that are part of the Conformance Group with the STATUS "mandatory" shall be present if the device supports the Conformance Group. Objects with the STATUS "optional" may be supported.

When a table is included in a Conformance Group, all objects contained in the table are included by reference. This is because a table is defined as a SEQUENCE OF {SEQUENCE}. Thus, all objects listed in the sequence are defined as an integral part of the table. Tables are defined as either mandatory or optional. If a table is mandatory, all of the objects with STATUS "mandatory" shall be present. If a table is optional, all of the objects with the STATUS "mandatory" shall be present if the device supports the table. Objects in the table with the STATUS "optional" may be supported.

B.1 NOTATION

The following notations and symbols are used to indicate status and conditional status within this standard.

B.1.1 TYPE Symbols

The following symbols are used to indicate type:

Symbol	Type
C	Control Object - use of 'dbCreateTransaction' in NTCIP 1201 Clause 2.3.1 shall NOT delay a SET to this object.
P	Parameter Object - use of 'dbCreateTransaction' in NTCIP 1201 Clause 2.3.1 to SET this object is optional.
P2	Parameter Object - use of 'dbCreateTransaction' in NTCIP 1201 Clause 2.3.1 to SET this object is mandatory.
S	Status / Information Object - this object is read only therefore a SET is not permitted.

B.1.2 Status Symbols

The following symbols are used to indicate status:

Symbol	Status
M	Mandatory
M.<n>	Support of every item of the group labeled by the same numeral <n> required, but only one is active at time.
O	Optional
O.<n>	Optional, but support of at least one of the group of options labeled by the same numeral <n> is required
C	Conditional
D	Deprecated
N/A	Non-applicable (i.e., logically impossible in the scope of the profile)
X	Excluded or prohibited

B.1.3 Conditional Status Notation

The following predicate notation is used:

Notation	Status
"<predicate>: M	Item is conditional on the <predicate>.

The <predicate>: notation means that the Status following it applies only when the feature or features identified by the predicate are supported. In the simplest case, <predicate> is the identifying tag of a single item.

B.1.4 Support Column

This section is in the form of a PICS and, therefore, includes a support column. An implementer claims support of an item by circling the appropriate answer (Yes or No) in the support column:

B.2 CCTV CAMERA CONTROL REQUIREMENTS

The Conformance Group definitions for CCTV Camera Control devices are defined in this clause. A CCTV Switch has multiple functions; thus, Conformance Groups are defined for each function.

The following table lists functional requirements for a CCTV Camera Control device, and asks if the listed features have been implemented.

Ref	Areas	Clause of Profile	Status	Support
B.3	CCTV Configuration Conformance Group	NTCIP 1205 – 3.2, 3.3 and 3.11	M	Yes
B.4	CCTV Extended Functions Conformance Group	NTCIP 1205 – 3.6, 3.7, 3.8, 3.9 and 3.10	O	Yes / No
B.5	CCTV Motion Control Conformance Group	NTCIP 1205 – 3.4 and 3.5	O	Yes / No
B.6	CCTV On-Screen Menu Control	NTCIP 1205 – 3.12	O	Yes / No
B.7	Configuration Conformance Group	NTCIP 1201 v01, Amendment 1	M	Yes
B.8	NTCIP Security Conformance Group	NTCIP 1201 v01, Amendment 1	M	Yes

CCTV Camera Control devices shall adhere to the conformance requirements specified in the above table as a minimum to claim compliance to this standard. Additional objects or groups may be supported without being non-compliant with CCTV Camera Control objects or NTCIP.

Minimum and maximum ranges of objects that differ from the values of the object's SYNTAX field may be enforced by an application running on a device.

A device which enforces range limits within the bounds specified by the values of the object's SYNTAX field shall not be categorized as being non-compliant with CCTV Camera Control objects or NTCIP.

A device which supports a subset of objects with enumerated values shall not be categorized as being non-compliant with CCTV Camera Control objects or NTCIP.

B.3 CCTV CONFIGURATION CONFORMANCE GROUP

The CCTV Configuration Conformance Group consists of the following objects:

CCTV Configuration CONFORMANCE GROUP						
NTCIP 1205 Amend 1 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
3.2, 3.3 and 3.11	**CCTV Configuration Conformance Group**	---	M	Yes	----	-----
3.2	**CCTV Range Objects**	---	---	---	---	---
3.2.1	rangeMaximumPreset	S	3.2 : M	Yes	0-255	
3.2.2	rangePanLeftLimit	S	3.2 : M	Yes	0-35999 | 65535	
3.2.3	rangePanRightLimit	S	3.2 : M	Yes	0-35999 | 65535	
3.2.4	rangePanHomePosition	S	3.2 : M	Yes	0-35999 | 65535	
3.2.5	rangeTrueNorthOffset	P	3.2 : M	Yes	0-35999 | 65535	
3.2.6	rangeTiltUpLimit	S	3.2 : M	Yes	0-35999 | 65535	
3.2.7	rangeTiltDownLimit	S	3.2 : M	Yes	0-35999 | 65535	
3.2.8	rangeZoomLimit	S	3.2 : M	Yes	0-65535	
3.2.9	rangeFocusLimit	S	3.2 : M	Yes	0-65535	
3.2.10	rangeIrisLimit	S	3.2 : M	Yes	0-65535	
3.2.11	rangeMinimumPanStepAngle	S	3.2 : M	Yes	0-35999 | 65535	
3.2.12	rangeMinimumTiltStepAngle	S	3.2 : M	Yes	0-35999 | 65535	
3.3	**CCTV Timeout Objects**	---	---	---	---	---
3.3.1	timeoutPan	P	3.3 : M	Yes	0-65535	
3.3.2	timeoutTilt	P	3.3 : M	Yes	0-65535	
3.3.3	timeoutZoom	P	3.3 : M	Yes	0-65535	
3.3.4	timeoutFocus	P	3.3 : M	Yes	0-65535	
3.3.5	timeoutIris	P	3.3 : M	Yes	0-65535	
3.11	**CCTV Label Objects**	---	---	---	---	---
3.11.1	labelMaximum	S	3.11 : M	Yes	0-255	
3.11.2	labelTable	---	3.11 : M	Yes	---	---
	labelEntry	---	3.11 : M	Yes	---	---
3.11.2.1	labelIndex	S	3.11 : M	Yes	0-255	
3.11.2.2	labelText	P	3.11 : M	Yes	String	
3.11.2.3	labelFontType	P	3.11 : D	Yes	0-255	
3.11.2.4	labelHeight	P	3.11 : M	Yes	0-255	
3.11.2.5	labelColor	P	3.11 : M	Yes	1-16	
	blue(1)	---	---	Yes / No	---	---
	green(2)	---	---	Yes / No	---	---
	cyan(3)	---	---	Yes / No	---	---
	red(4)	---	---	Yes / No	---	---
	magenta(5)	---	---	Yes / No	---	---
	brown(6)	---	---	Yes / No	---	---
	white(7)	---	---	Yes	---	---
	grey(8)	---	---	Yes / No	---	---
	lightBlue(9)	---	---	Yes / No	---	---
	lightGreen(10)	---	---	Yes / No	---	---
	lightCyan(11)	---	---	Yes / No	---	---
	lightRed(12)	---	---	Yes / No	---	---
	lightMagenta(13)	---	---	Yes / No	---	---
	yellow(14)	---	---	Yes / No	---	---
	brightWhite(15)	---	---	Yes / No	---	---
	black(16)	---	---	Yes / No	---	---
3.11.2.6	labelStartRow	P	3.11 : M	Yes	0-255	

CCTV Configuration CONFORMANCE GROUP						
NTCIP 1205 Amend 1 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
3.11.2.7	labelStartColumn	P	3.11 : M	Yes	0-255	
3.11.2.8	labelStatus	S	3.11 : M	Yes	String	
	bit 7 – Label is Valid for Display	---	---	Yes	---	---
	bit 6 – Display Status of Label	---	---	Yes	---	---
	bit 5 – Reserved	---	---	---	---	---
	bit 4 – Reserved	---	---	---	---	---
	bit 3 – Reserved	---	---	---	---	---
	bit 2 – Reserved	---	---	---	---	---
	bit 1 – Reserved	---	---	---	---	---
	bit 0 – Reserved	---	---	---	---	---
3.11.2.9	labelActive	P	3.11 : M	Yes	String	
	bit 7 – Display Label	---	---	Yes	---	---
	bit 6 – Reserved	---	---	---	---	---
	bit 5 – Reserved	---	---	---	---	---
	bit 4 – Reserved	---	---	---	---	---
	bit 3 – Reserved	---	---	---	---	---
	bit 2 – Reserved	---	---	---	---	---
	bit 1 – Reserved	---	---	---	---	---
	bit 0 – Reserved	---	---	---	---	---
3.11.2.9	labelFontNumber	P	3.11 : M	Yes	1-255	
3.11.3	labelLocationLabel	P	3.11 : M	Yes	0-255	
3.11.4	labelEnableTextDisplay	P	3.11 : M	Yes	String	
	bit 7 – Display All Labels at Once	---	---	Yes	---	---
	bit 6 – Reserved	---	---	---	---	---
	bit 5 – Reserved	---	---	---	---	---
	bit 4 – Reserved	---	---	---	---	---
	bit 3 – Reserved	---	---	---	---	---
	bit 2 – Reserved	---	---	---	---	---
	bit 1 – Reserved	---	---	---	---	---
	bit 0 – Reserved	---	---	---	---	---

B.4 CCTV EXTENDED FUNCTIONS CONFORMANCE GROUP

The CCTV Extended Functions Conformance Group consists of the following objects:

CCTV Extended Functions CONFORMANCE GROUP						
NTCIP 1205 Amend 1 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
3.6, 3.7, 3.8, 3.9 and 3.10	**CCTV Extended Functions Conformance Group**	---	O	Yes / No	---	---
3.6	**CCTV System Feature Control Objects**	---	---	---	---	---
3.6.1	systemCameraFeatureControl	C	3.6 : M	Yes	String	
	Byte 1, bit 7 – Camera Power Select	---	---	Yes	---	---
	Byte 1, bit 6 – Heater Power Select	---	---	Yes	---	---
	Byte 1, bit 5 – Wiper Select	---	---	Yes	---	---
	Byte 1, bit 4 – Washer Select	---	---	Yes	---	---
	Byte 1, bit 3 – Blower Select	---	---	Yes	---	---
	Byte 1, bit 2 – Reserved	---	---	---	---	---
	Byte 1, bit 1 – Reserved	---	---	---	---	---
	Byte 1, bit 0 – Reserved	---	---	---	---	---
	Byte 2, bit 7 – Activation and Deactivation of the Camera Component	---	---	Yes	---	---
	Byte 2, bit 6 – Reserved	---	---	---	---	---
	Byte 2, bit 5 – Reserved	---	---	---	---	---
	Byte 2, bit 4 – Reserved	---	---	---	---	---
	Byte 2, bit 3 – Reserved	---	---	---	---	---
	Byte 2, bit 2 – Reserved	---	---	---	---	---
	Byte 2, bit 1 – Reserved	---	---	---	---	---
	Byte 2, bit 0 – Reserved	---	---	---	---	---
3.6.2	systemCameraFeatureStatus	S	3.6 : M	Yes	String	
	bit 7 – Camera Power Status	---	---	Yes	---	---
	bit 6 – Heater Power Status	---	---	Yes	---	---
	bit 5 – Wiper Status	---	---	Yes	---	---
	bit 4 – Washer Status	---	---	Yes	---	---
	bit 3 – Blower Status	---	---	Yes	---	---
	bit 2 – Reserved	---	---	---	---	---
	bit 1 – Reserved	---	---	---	---	---
	bit 0 – Reserved	---	---	---	---	---
3.6.3	systemCameraEquipped	S	3.6 : M	Yes	String	
	bit 7 – Camera Power Available	---	---	Yes	---	---
	bit 6 – Heater Power Available	---	---	Yes	---	---
	bit 5 – Wiper Available	---	---	Yes	---	---
	bit 4 – Washer Available	---	---	Yes	---	---
	bit 3 – Blower Available	---	---	Yes	---	---
	bit 2 – Reserved	---	---	---	---	---
	bit 1 – Reserved	---	---	---	---	---
	bit 0 – Reserved	---	---	---	---	---
3.6.4	systemLensFeatureControl	C	3.6 : M	Yes	String	
	Byte 1, bit 7 – Auto Iris Select	---	---	Yes	---	---
	Byte 1, bit 6 – Auto Focus Select	---	---	Yes	---	---
	Byte 1, bit 5 – Reserved	---	---	---	---	---
	Byte 1, bit 4 – Reserved	---	---	---	---	---
	Byte 1, bit 3 – Reserved	---	---	---	---	---
	Byte 1, bit 2 – Reserved	---	---	---	---	---
	Byte 1, bit 1 – Reserved	---	---	---	---	---
	Byte 1, bit 0 – Reserved	---	---	---	---	---
	Byte 2, bit 7 – Activation and Deactivation of the Lens Component	---	---	Yes	---	---
	Byte 2, bit 6 – Reserved	---	---	---	---	---
	Byte 2, bit 5 – Reserved	---	---	---	---	---
	Byte 2, bit 4 – Reserved	---	---	---	---	---
	Byte 2, bit 3 – Reserved	---	---	---	---	---
	Byte 2, bit 2 – Reserved	---	---	---	---	---
	Byte 2, bit 1 – Reserved	---	---	---	---	---
	Byte 2, bit 0 – Reserved	---	---	---	---	---
3.6.5	systemLensFeatureStatus	S	3.6 : M	Yes	String	
	bit 7 – Auto Iris Status	---	---	Yes	---	---

CCTV Extended Functions CONFORMANCE GROUP						
NTCIP 1205 Amend 1 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
	bit 6 – Auto Focus Status	---	---	Yes	---	---
	bit 5 – Reserved	---	---	---	---	---
	bit 4 – Reserved	---	---	---	---	---
	bit 3 – Reserved	---	---	---	---	---
	bit 2 – Reserved	---	---	---	---	---
	bit 1 – Reserved	---	---	---	---	---
	bit 0 – Reserved	---	---	---	---	---
3.6.6	systemLensEquipped	S	3.6 : M	Yes	String	
	bit 7 – Auto Iris Available	---	---	Yes	---	---
	bit 6 – Auto Focus Available	---	---	Yes	---	---
	bit 5 – Reserved	---	---	---	---	---
	bit 4 – Reserved	---	---	---	---	---
	bit 3 – Reserved	---	---	---	---	---
	bit 2 – Reserved	---	---	---	---	---
	bit 1 – Reserved	---	---	---	---	---
	bit 0 – Reserved	---	---	---	---	---
3.7	**CCTV Alarm Objects**	---	---	---	---	---
3.7.1	alarmStatus	S	3.7 : M	Yes	String	
	bit 7 – Cabinet Alarm Status	---	---	Yes	---	---
	bit 6 – Enclosure Alarm Status	---	---	Yes	---	---
	bit 5 – Video Loss Alarm Status	---	---	Yes	---	---
	bit 4 – Temperature Alarm Status	---	---	Yes	---	---
	bit 3 – Pressure Alarm Status	---	---	Yes	---	---
	bit 2 – Local/Remote Alarm Status	---	---	Yes	---	---
	bit 1 – Washer Fluid Alarm Status	---	---	Yes	---	---
	bit 0 – Reserved	---	---	---	---	---
3.7.2	alarmLatchStatus	S	3.7 : M	Yes	String	
	bit 7 – Cabinet Alarm Latch Status	---	---	Yes	---	---
	bit 6 – Enclosure Alarm Latch Status	---	---	Yes	---	---
	bit 5 – Video Loss Alarm Latch Status	---	---	Yes	---	---
	bit 4 – Temperature Alarm Latch Status	---	---	Yes	---	---
	bit 3 – Pressure Alarm Latch Status	---	---	Yes	---	---
	bit 2 – Local/Remote Alarm Latch Status	---	---	Yes	---	---
	bit 1 – Washer Fluid Alarm Latch Status	---	---	Yes	---	---
	bit 0 – Reserved	---	---	---	---	---
3.7.3	alarmLatchClear	P	3.7 : M	Yes	String	
	bit 7 – Cabinet Alarm Latch Clear	---	---	Yes	---	---
	bit 6 – Enclosure Alarm Latch Clear	---	---	Yes	---	---
	bit 5 – Video Loss Alarm Latch Clear	---	---	Yes	---	---
	bit 4 – Temperature Alarm Latch Clear	---	---	Yes	---	---
	bit 3 – Pressure Alarm Latch Clear	---	---	Yes	---	---
	bit 2 – Local/Remote Alarm Latch Clear	---	---	Yes	---	---
	bit 1 – Washer Fluid Alarm Latch Clear	---	---	Yes	---	---
	bit 0 – Reserved	---	---	---	---	---
3.7.4	alarmTemperatureHighLowThreshold	P	3.7 : M	Yes	String	
	Byte 1 – Low Temperature Threshold	---	---	Yes	---	---
	Byte 2 – High Temperature Threshold	---	---	Yes	---	---
3.7.5	alarmTemperatureCurrentValue	S	3.7 : M	Yes	String	
	Byte 1 – Current Temperature Value	---	---	Yes	---	---
3.7.6	alarmPressurehighLowThreshold	P	3.7 : M	Yes	String	
	Byte 1 – Low Pressure Threshold	---	---	Yes	---	---
	Byte 2 – High Pressure Threshold	---	---	Yes	---	---
3.7.7	alarmPressureCurrentValue	S	3.7 : M	Yes	String	
	Byte 1 – Current Pressure Value	---	---	Yes	---	---
3.7.8	alarmWasherFluidHighLowThreshold	P	3.7 : M	Yes	String	
	Byte 1 – Low Washer Fluid Threshold	---	---	Yes	---	---
	Byte 2 – High Washer Fluid Threshold	---	---	Yes	---	---
3.7.9	alarmWasherFluidCurrentValue	S	3.7 : M	Yes	String	
	Byte 1 – Current Washer Fluid Value	---	---	Yes	---	---

CCTV Extended Functions CONFORMANCE GROUP						
NTCIP 1205 Amend 1 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
3.7.10	alarmLabelIndex	---	---	Yes	---	---
	Byte 1 – Cabinet Alarm Label Number	---	---	Yes	---	---
	Byte 2 – Enclosure Alarm Label Number	---	---	Yes	---	---
	Byte 3 – Video Loss Alarm Label Number	---	---	Yes	---	---
	Byte 4 – Temperature Alarm Label Number	---	---	Yes	---	---
	Byte 5 – Pressure Alarm Label Number	---	---	Yes	---	---
	Byte 6 – Local/Remote Alarm Label Number	---	---	Yes	---	---
	Byte 7 – Washer Fluid Alarm Label Number	---	---	Yes	---	---
3.7.11	alarmLabelSource	P	3.7 : M	Yes	String	
	bit 7 – Cabinet Alarm Latch Status	---	---	Yes	---	---
	bit 6 – Enclosure Alarm Latch Status	---	---	Yes	---	---
	bit 5 – Video Loss Alarm Latch Status	---	---	Yes	---	---
	bit 4 – Temperature Alarm Latch Status	---	---	Yes	---	---
	bit 3 – Pressure Alarm Latch Status	---	---	Yes	---	---
	bit 2 – Local/Remote Alarm Latch Status	---	---	Yes	---	---
	bit 1 – Washer Fluid Alarm Latch Status	---	---	Yes	---	---
	bit 0 – Reserved	---	---	---	---	---
3.8	**CCTV Discrete Input Objects**	---	---	---	---	---
3.8.1	inputStatus	S	3.8 : M	Yes	String	
	bit 7 – Discrete Input 8 Active Status	---	---	Yes	---	---
	bit 6 – Discrete Input 7 Active Status	---	---	Yes	---	---
	bit 5 – Discrete Input 6 Active Status	---	---	Yes	---	---
	bit 4 – Discrete Input 5 Active Status	---	---	Yes	---	---
	bit 3 – Discrete Input 4 Active Status	---	---	Yes	---	---
	bit 2 – Discrete Input 3 Active Status	---	---	Yes	---	---
	bit 1 – Discrete Input 2 Active Status	---	---	Yes	---	---
	bit 0 – Discrete Input 1 Active Status	---	---	Yes	---	---
3.8.2	inputLatchStatus	S	3.8 : M	Yes	String	
	bit 7 – Discrete Input 8 Latch Status	---	---	Yes	---	---
	bit 6 – Discrete Input 7 Latch Status	---	---	Yes	---	---
	bit 5 – Discrete Input 6 Latch Status	---	---	Yes	---	---
	bit 4 – Discrete Input 5 Latch Status	---	---	Yes	---	---
	bit 3 – Discrete Input 4 Latch Status	---	---	Yes	---	---
	bit 2 – Discrete Input 3 Latch Status	---	---	Yes	---	---
	bit 1 – Discrete Input 2 Latch Status	---	---	Yes	---	---
	bit 0 – Discrete Input 1 Latch Status	---	---	Yes	---	---
3.8.3	inputLatchClear	C	3.8 : M	Yes	String	
	bit 7 – Discrete Input 8 Latch Clear	---	---	Yes	---	---
	bit 6 – Discrete Input 7 Latch Clear	---	---	Yes	---	---
	bit 5 – Discrete Input 6 Latch Clear	---	---	Yes	---	---
	bit 4 – Discrete Input 5 Latch Clear	---	---	Yes	---	---
	bit 3 – Discrete Input 4 Latch Clear	---	---	Yes	---	---
	bit 2 – Discrete Input 3 Latch Clear	---	---	Yes	---	---
	bit 1 – Discrete Input 2 Latch Clear	---	---	Yes	---	---
	bit 0 – Discrete Input 1 Latch Clear	---	---	Yes	---	---
3.8.4	inputLabelIndex	P	3.8 : M	Yes	String	
	Byte 1 – Discrete Input 1 Label Number	---	---	Yes	---	---
	Byte 2 – Discrete Input 2 Label Number	---	---	Yes	---	---
	Byte 3 – Discrete Input 3 Label Number	---	---	Yes	---	---
	Byte 4 – Discrete Input 4 Label Number	---	---	Yes	---	---
	Byte 5 – Discrete Input 5 Label	---	---	Yes	---	---

CCTV Extended Functions CONFORMANCE GROUP						
NTCIP 1205 Amend 1 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
	Number					
	Byte 6 – Discrete Input 6 Label Number	---	---	Yes	---	---
	Byte 7 – Discrete Input 7 Label Number	---	---	Yes	---	---
	Byte 8 – Discrete Input 8 Label Number	---	---	Yes	---	---
3.8.5	inputPresetIndex	P	3.8 : M	Yes	String	
	Byte 1 – Discrete Input 1 Preset Number	---	---	Yes	---	---
	Byte 2 – Discrete Input 2 Preset Number	---	---	Yes	---	---
	Byte 3 – Discrete Input 3 Preset Number	---	---	Yes	---	---
	Byte 4 – Discrete Input 4 Preset Number	---	---	Yes	---	---
	Byte 5 – Discrete Input 5 Preset Number	---	---	Yes	---	---
	Byte 6 – Discrete Input 6 Preset Number	---	---	Yes	---	---
	Byte 7 – Discrete Input 7 Preset Number	---	---	Yes	---	---
	Byte 8 – Discrete Input 8 Preset Number	---	---	Yes	---	---
3.8.6	inputLabelSource	P	3.8 : M	Yes	String	
	bit 7 – Discrete Input 8 Label Source	---	---	Yes	---	---
	bit 6 – Discrete Input 7 Label Source	---	---	Yes	---	---
	bit 5 – Discrete Input 6 Label Source	---	---	Yes	---	---
	bit 4 – Discrete Input 5 Label Source	---	---	Yes	---	---
	bit 3 – Discrete Input 4 Label Source	---	---	Yes	---	---
	bit 2 – Discrete Input 3 Label Source	---	---	Yes	---	---
	bit 1 – Discrete Input 2 Label Source	---	---	Yes	---	---
	bit 0 – Discrete Input 1 Label Source	---	---	Yes	---	---
3.9	**CCTV Discrete Output Objects**	---	---	---	---	---
3.9.1	outputStatus	S	3.9 : M	Yes	String	
	bit 7 – Discrete Output 8 Active Status	---	---	Yes	---	---
	bit 6 – Discrete Output 7 Active Status	---	---	Yes	---	---
	bit 5 – Discrete Output 6 Active Status	---	---	Yes	---	---
	bit 4 – Discrete Output 5 Active Status	---	---	Yes	---	---
	bit 3 – Discrete Output 4 Active Status	---	---	Yes	---	---
	bit 2 – Discrete Output 3 Active Status	---	---	Yes	---	---
	bit 1 – Discrete Output 2 Active Status	---	---	Yes	---	---
	bit 0 – Discrete Output 1 Active Status	---	---	Yes	---	---
3.9.2	outputControl	C	3.9 : M	Yes	String	
	Byte 1, bit 7 – Discrete Output 8 Control	---	---	Yes	---	---
	Byte 1, bit 6 – Discrete Output 7 Control	---	---	Yes	---	---
	Byte 1, bit 5 – Discrete Output 6 Control	---	---	Yes	---	---
	Byte 1, bit 4 – Discrete Output 5 Control	---	---	Yes	---	---
	Byte 1, bit 3 – Discrete Output 4 Control	---	---	Yes	---	---
	Byte 1, bit 2 – Discrete Output 3 Control	---	---	Yes	---	---
	Byte 1, bit 1 – Discrete Output 2 Control	---	---	Yes	---	---
	Byte 1, bit 0 – Discrete Output 1 Control	---	---	Yes	---	---
	Byte 2, bit 7 – Discrete Output 8 Active	---	---	Yes	---	---
	Byte 2, bit 6 – Discrete Output 7 Active	---	---	Yes	---	---
	Byte 2, bit 5 – Discrete Output 6 Active	---	---	Yes	---	---

CCTV Extended Functions CONFORMANCE GROUP						
NTCIP 1205 Amend 1 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
	Byte 2, bit 4 – Discrete Output 5 Active	---	---	Yes	---	---
	Byte 2, bit 3 – Discrete Output 4 Active	---	---	Yes	---	---
	Byte 2, bit 2 – Discrete Output 3 Active	---	---	Yes	---	---
	Byte 2, bit 1 – Discrete Output 2 Active	---	---	Yes	---	---
	Byte 2, bit 0 – Discrete Output 1 Active	---	---	Yes	---	---
3.9.3	outputLabelIndex	P	3.9 : M	Yes	String	
	Byte 1 – Discrete Output 1 Label Number	---	---	Yes	---	---
	Byte 2 – Discrete Output 2 Label Number	---	---	Yes	---	---
	Byte 3 – Discrete Output 3 Label Number	---	---	Yes	---	---
	Byte 4 – Discrete Output 4 Label Number	---	---	Yes	---	---
	Byte 5 – Discrete Output 5 Label Number	---	---	Yes	---	---
	Byte 6 – Discrete Output 6 Label Number	---	---	Yes	---	---
	Byte 7 – Discrete Output 7 Label Number	---	---	Yes	---	---
	Byte 8 – Discrete Output 8 Label Number	---	---	Yes	---	---
3.10	**CCTV Zone Objects**	---	---	---	---	---
3.10.1	zoneMaximum	S	3.10 : M	Yes	0-255	
3.10.2	zoneTable	---	3.10 : M	Yes	---	---
	zoneEntry	---	3.10 : M	Yes	---	---
3.10.2.1	zoneIndex	S	3.10 : M	Yes	0-255	
3.10.2.2	zoneLabel	P	3.10 : M	Yes	0-255	
3.10.2.3	zonePanLeftLimit	P	3.10 : M	Yes	1-35999 | 65535	
3.10.2.4	zonePanRightLimit	P	3.10 : M	Yes	1-35999 | 65535	
3.10.2.5	zoneTiltUpLimit	P	3.10 : M	Yes	1-35999 | 65535	
3.10.2.6	zoneTiltDownLimit	P	3.10 : M	Yes	1-35999 | 65535	
3.10.2.7	zoneVideoControl	C	3.10 : M	Yes	String	
	bit 7 – Video Signal Output Control	---	---	Yes	---	---
	bit 6 – Reserved	---	---	---	---	---
	bit 5 – Reserved	---	---	---	---	---
	bit 4 – Reserved	---	---	---	---	---
	bit 3 – Reserved	---	---	---	---	---
	bit 2 – Reserved	---	---	---	---	---
	bit 1 – Reserved	---	---	---	---	---
	bit 0 – Reserved	---	---	---	---	---
3.10.3	zoneCameraEquipped	S	3.10 : M	Yes	String	
	bit 7 – Zones Availability	---	---	Yes	---	---
	bit 6 – Zone Labels Availability	---	---	Yes	---	---
	bit 5 – Video Signal Control Availability	---	---	Yes	---	---
	bit 4 – Reserved	---	---	---	---	---
	bit 3 – Reserved	---	---	---	---	---
	bit 2 – Reserved	---	---	---	---	---
	bit 1 – Reserved	---	---	---	---	---
	bit 0 – Reserved	---	---	---	---	---

B.5 CCTV MOTION CONTROL CONFORMANCE GROUP

The CCTV Motion Control Conformance Group shall consist of the following objects:

CCTV Motion Control CONFORMANCE GROUP

NTCIP 1205 Amend 1 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
3.4 and 3.5	**CCTV Motion Control Conformance Group**	---	O	Yes / No	----	-----
3.4	**CCTV Preset Objects**	---	---	---	---	---
3.4.1	presetGotoPosition	C	3.4 : M	Yes	1-255	
3.4.2	presetStorePosition	P	3.4 : M	Yes	1-255	
3.4.3	presetPositionQuery	S	3.4 : M	Yes	0-255	
3.5	**CCTV Positioning Objects**	---	---	---	---	---
3.5.1	positionPan PositionReference	C ---	3.5 : M ---	Yes Yes	String ---	 ---
3.5.2	positionTilt PositionReference	C ---	3.5 : M ---	Yes Yes	String ---	 ---
3.5.3	positionZoomLens PositionReference	C ---	3.5 : M ---	Yes Yes	String ---	 ---
3.5.4	positionFocusLens PositionReference	C ---	3.5 : M ---	Yes Yes	String ---	 ---
3.5.5	positionIrisLens PositionReference	C ---	3.5 : M ---	Yes Yes	String ---	 ---
3.5.6	positionQueryPan	S	3.5 : M	Yes	1-35999 | 65535	
3.5.7	positionQueryTilt	S	3.5 : M	Yes	1-35999 | 65535	
3.5.8	positionQueryZoom	S	3.5 : M	Yes	1-65535	
3.5.9	positionQueryFocus	S	3.5 : O	Yes / No	1-65535	
3.5.10	positionQueryIris	S	3.5 : O	Yes / No	1-65535	

B.6 CCTV ON-SCREEN MENU CONTROL CONFORMANCE GROUP

The CCTV On-Screen Menu Control Conformance Group shall consist of the following objects:

CCTV On-Screen Menu Control CONFORMANCE GROUP						
NTCIP 1205 Amend 1 Clause	**Object Name**	**Object Type**	**Object Status**	**Object Support**	**Allowed Values**	**Supported Values**
3.12	**CCTV On-Screen Menu Control Conformance Group**	---	O	Yes / No	----	-----
3.12	**CCTV On-Screen Camera Menu Objects**	---	---	---	---	---
3.12.1	menuActivate	P	3.12 : M	Yes	0-255	---
3.12.2	menuControl	C	3.12 : M	Yes	1-255	
	pageDown(1)	---	---	Yes / No	---	---
	pageUp(2)	---	---	Yes / No	---	---
	cursorUp(3)	---	---	Yes / No	---	---
	cursorDown(4)	---	---	Yes / No	---	---
	cursorRight(5)	---	---	Yes / No	---	---
	incrementValue(7)	---	---	Yes / No	---	---
	decrementValue(8)	---	---	Yes / No	---	---
	enterValue(9)	---	---	Yes / No	---	---
	noMenu(255)	---	---	Yes / No	---	---

B.7 GLOBAL CONFIGURATION CONFORMANCE GROUP

The Global Configuration Conformance Group shall consist of the following objects:

Global Configuration CONFORMANCE GROUP						
NTCIP 1201 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
2.2	**Global Config Objects**	---	M	Yes	---	---
2.2.1	globalSetIDParmeter	S	2.2 : O	Yes / No	0-65535	
2.2.2	globalMaxModules	S	2.2 : M	Yes	0-255	
2.2.3	globalModuleTable	---	2.2 : M	Yes	---	---
	moduleTableEntry	---	2.2 : M	Yes	---	---
2.2.3.1	moduleNumber	S	2.2 : M	Yes	1-255	
2.2.3.2	moduleDeviceNode	S	2.2 : M	Yes	OID	
2.2.3.3	moduleMake	S	2.2 : M	Yes	String	
2.2.3.4	moduleModel	S	2.2 : M	Yes	String	
2.2.3.5	moduleVersion	S	2.2 : M	Yes	String	
2.2.3.6	moduleType	S	2.2 : M	Yes	1-3	
	other(1)	---	---	Yes / No	---	---
	hardware(2)	---	---	Yes / No	---	---
	software(3)	---	---	Yes / No	---	---

B.8 NTCIP SECURITY CONFORMANCE GROUP

The NTCIP Security Conformance Group shall consist of the following objects:

Security CONFORMANCE GROUP						
NTCIP 1201 Amend 1 Clause	Object Name	Object Type	Object Status	Object Support	Allowed Values	Supported Values
A.10	**Security Conformance Group**	--	M	Yes	----	---
A.10.1	adminCommunityName	C	A.10 : M	Yes	String	
A.10.2	maxCommunityNames	C	A.10 : M	Yes	1..255	
A.10.3	communityNameTable	--	A.10 : M	Yes	---	
	communityNameTableEntry	--	A.10 : M	Yes	---	
A.10.3.1	communityNameIndex	S	A.10 : M	Yes	1..255	
A.10.3.2	communityNameUser	S	A.10 : M	Yes	String	
A.10.3.3	communityNameAccessMask	S	A.10 : M	Yes	Gauge	

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